





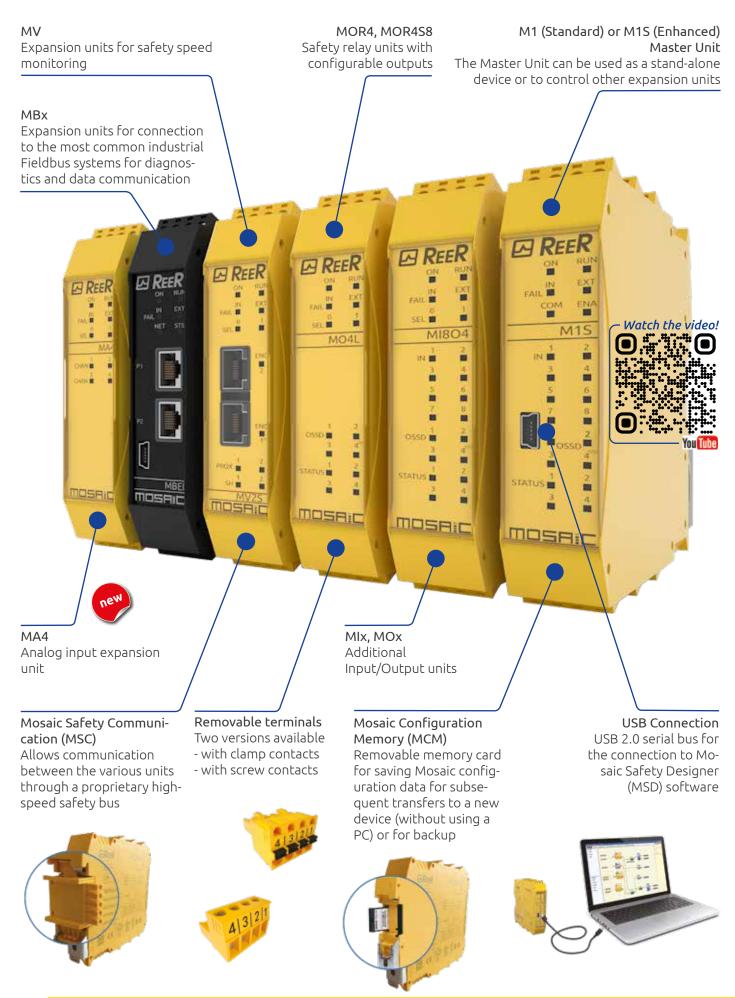




## modular safety integrated controller

## product catalogue

Wolf Process Automation Limited | Tel: +353 45 831575 | Email: info@wpa.ie | Web: www.wpa.ie



### **KEY FEATURES**

Mosaic is a safety hub able to manage all safety functions of a machinery. **Configurable and scalable**, allows **cost reductions** and **minimal wiring** 

 $\bigcirc$ 

Mosaic can manage safety sensors and signals such as:

- Light curtains
- Photocells
- Laser scanners
- Emergency stops
- Electromechanical switches
- Guard-lock safety door switches
- Magnetic switches
- RFID switches
- Inductive sensors
- Safety mats and edges
- Two-hands controls
- Hand grip switches
- Safety switch with guard locking
- Encoders and proximities for safety speed control
- Loading cells, pressure switches, temperature measurements, flow and level measurements

### ADVANTAGES

Compared to "traditional" electromechanical safety-relays-based safety circuitries, Mosaic has the following advantages:

Reducing the number of devices and wiring used and, therefore, the overall size of the project

Speeding-up control panel construction

Providing **logic configuration** via a quick and **easy-to-use software**. Machine designers are always able to change configuration logic

Master units M1 and M1S configurable via the MSD (Mosaic Safety Designer) graphic interface (provided with each Master units at no extra cost)

Simply adding or removing safety function blocks at any stage of machine design

Is able to check the logic configuration of the application during the designing phase through the **validation** function and Simulation as well as to test it during the installation through the monitor function

Allows tamper-proof system configurations as:

- detection of tempering attempts through specific tests (i.e. mandatory test of the safety device at machine start-up)
- protection against unauthorized changes to the project through a 2-level password

| All logic is configured through a graphic interface. No more laborious wiring is needed as with tra | aditional |
|---|-----------|
| solutions   |           |

A lower number of electromechanical components also means a **better Performance Level** and, therefore, a **higher Safety Level** 

The project report provides the actual values of PFH<sub>d</sub>, DC<sub>ava</sub> and MTTF<sub>d</sub> according to EN 13849-1 and EN 62061







### M1

Standard Master Unit

8 digital inputs 2 inputs for Start/Restart interlock and EDM 2 pairs OSSD safety outputs (PNP 400 mA) 2 status outputs (PNP 100 mA) 4 test outputs (for short-circuits monitoring)

Not compatible with the following expansion units: MA4, MI8O4, MO4L

## Connect up to 14 expansions...

#### Additional inputs



### MI8 / MI16 / MI12T8 / MA4

#### Input expansion units

**MI8** 

#### 8 digital inputs

4 test outputs (for short-circuits monitoring)

#### MI16

16 digital inputs 4 test outputs (for short-circuits monitoring)

#### MI12T8

12 digital inputs 8 test outputs (for short-circuits monitoring) Can manage up to 4 independent safety mats/edges



4 indipendent isolated analogue channels (500 V) Each channel can supply 24V DC up to 30 mA Each channel can detect a 4-20 mA current or a 0-10V voltage (selectable via software)



Additional outputs

### MO2 / MO4 / MO4L HC S8 / MO4L

#### Output expansion units

MO2

2 pairs OSSD safety outputs (PNP 400 mA)2 inputs for Start/Restart interlock and EDM2 status outputs (PNP 100 mA)

#### MO4

4 pairs OSSD safety outputs (PNP 400 mA) 4 inputs for Start/Restart interlock and EDM 4 status outputs (PNP 100 mA)

#### MO4L HC S8 POWER

4 single OSSD safety outputs or 2 pairs(PNP 2,0 A for each channel, total current 8 A)4 inputs for Start/Restart interlock and EDM8 status outputs (PNP 100 mA)



4 single OSSD safety outputs or 2 pairs (PNP 400 mA)4 inputs for Start/Restart interlock and EDM4 status outputs (PNP 100 mA)

### Speed monitoring

REF



### MV0 / MV1 / MV2

#### Speed monitoring expansion units

Safety speed monitoring (up to PL e) for: zero speed control, maximum speed control, speed range control, direction contol

#### MV0

Inputs for 2 proximity switches

#### MV1

Inputs for 1 incremental encoder and 2 proximity switches (TTL, HTL o SIN/COS)

#### MV2

Inputs for 2 incremental encoders and 2 proximity switches (TTL, HTL o SIN/COS)



### M1S

Enhanced Master Unit

- 8 digital inputs 4 inputs for Start/Restart interlock and EDM
- 4 single OSSD safety outputs, or 2 pairs (PNP 400 mA)
- 4 status outputs (PNP 100 mA)
- 4 test outputs (for short-circuits monitoring)

Compatible with all expansion units



## ...to the Master Units

### Safety relays

### Communication

Additional inputs/outputs

Additional status outputs



### MOR4 / MOR4 S8 / MR2 / MR4

Safety relay output expansion units MR2

2 safety relays with guided contacts 2 NO + 1 NC contacts (250 VAC 6 A) 1 NC contacts for EDM feedback

#### MR4

4 safety relays with guided contacts 4 NO + 2 NC contacts (240 VAC 6 A) 2 NC contacts for EDM feedback

#### MOR4

4 safety relays with guided contacts

4 NO contacts (250 VAC 6 A)

It is possible to select two different configurations via MSD:

- 4 independent single channel outputs

- 2 dual channel outputs

4 inputs for Start/Restart interlock and EDM Single channel LED signaling

#### MOR4S8

As MOR4, with 8 status outputs (PNP 100 mA)



### MCT

Field-bus interface units Profibus DP DeviceNET CANopen EthernetIP EtherCAT Profinet Modbus RTU Modbus TCP CC-Link USB

MBx

transfer Interface unit allowing the connection of remote expansions via proprietary

Mosaic bus

MSC bus

TCP 1 connection

interface (1 I/O)

#### MCT2

2 connections interface (2 I/O)



### MI8O2 / MI8O4

Input/Output expansion units MI8O2

#### .....

8 digital inputs 2 inputs for Start/Restart interlock and EDM

2 pairs OSSD safety outputs (PNP 400 mA)

2 status outputs (PNP 100 mA) 4 test outputs (forshort-circuits monitoring)

#### MI804

8 digital inputs 4 inputs for Start/Restart interlock and EDM

4 single OSSD safety outputs or 2 pairs (PNP 400 mA)

4 status outputs (PNP 100 mA)

4 test outputs (for short-circuits monitoring)



### MOS8 / MOS16

Status output expansion units

#### MOS 8

8 status outputs \* (PNP 100 mA)

#### MOS16

16 status outputs \* (PNP 100 mA)

new

\* Safety Level of status outputs: SIL 1 - SILCL1 - PL c - Cat.1





DIGITAL INPUTS

SAFETY OUTPUTS 2 pairs OSSD

EDM/RESTART

TEST OUTPUTS

STATUS OUTPUTS 2

LOGICAL OPERATORS 64

### APPROVALS

- 2006/42/EC: "Machine Directive"
- 2014/30/EU: "Electromagnetic Compatibility Directive".
- 2014/35/EU: "Low Voltage Directive"
- EN 61496-1:2013 (Type 4) "Safety of machinery Electro sensitive protective equipment - General requirements and tests"
- EN 61131-2:2007 "Programmable controllers Part 2. Equipment requirements and tests"
- EN 61508-1:2010 (SIL3) "Functional safety of electrical / electronic / programmable electronic safety related systems General requirements"
- EN 61508-2:2010 (SIL3) "Functional safety of electrical / electronic / programmable electronic safety related systems -Requirements for electrical/electronic/programmable electronic safety-related systems"
- EN 61508-3:2010 (SIL3) "Functional safety of electrical / electronic / programmable electronic safety related systems: Software requirements"
- EN 61508-4:2010 (SIL3) "Functional safety of electrical / electronic / programmable electronic safety related systems -Definitions and abbreviations"
- IEC 62061:2005/A2:2015 (SILCL 3) "Safety of machinery -Functional safety of safety-related electrical, electronic and programmable electronic control systems"
- EN ISO 13849-1:2008 (Cat. 4 PL e) "Safety of machinery Safety-related parts of control systems - Part 1: General principles for design"
- IEC 61784-3:2008 "Industrial communication networks -Profiles - Part 3: Functional safety fieldbuses - General rules and profile definitions"
- UNI EN 81-20:2014 "Safety rules for the construction and installation of lifts. Lifts for the transport of persons and goods. Part 20: Passenger and goods passenger lift"
- UNI EN 81-50:2014 "Safety rules for the construction and installation of lifts. Examinations and test. Part 50: Design rules, calculations, examinations and tests of lift components"
- UL (C+US) mark for USA and Canada
- ANSI / UL 1998: "Safety Software in Programmable Components"
- The S-Mark carries the same weight in Korea as the CE-Mark does in Europe



### M1

### STANDARD MASTER UNIT

Master unit, also usable as a stand-alone device, able to control any other expansion unit (not compatible with: MI8O4, MO4L and MA4). With 8 digital inputs and 2 pairs OSSD safety outputs.

### APPLICATION EXAMPLE

**Stand-alone**: To provide protection for a smaller machinery connecting for example 1 safety light curtain, 1 e-stop, 1 magnetic sensor and 1 two-hand switch.

As Master unit: To control a more complex system providing protection for bigger machineries.

### TECHNICAL FEATURES

| Digital inputs     | 8 digital inputs  |
|--------------------|---|
| Safety outputs     | 2 pairs OSSD (PNP 400 mA output current)                                  |
| EDM                | 2 inputs for Start/Restart interlock and external device monitoring (EDM) |
| Status outputs     | 2 programmable digital signal outputs<br>(PNP 100 mA output current)      |
| Test outputs       | 4 test outputs for sensor monitoring                                      |
| LED signalling     | Input/output status and fault diagnostics                                 |
| Configuration      | With PC via USB interface using MSD (Mosaic<br>Safety Designer) software  |
| MSC bus connection | With MSC connector (optional)   |
| МСМ                | Mosaic Configuration Memory (optional)                                    |

### ACCESSORIES

**MSC Rear Bus connector**: necessary to connect the Master unit to any expansion unit. As the Master unit can be used as stand-alone, the bus connector must be ordered separately.

MCM Card (Mosaic Configuration Memory): memory card designed to store the Master unit configuration as a backup. Can be used to restore the saved configuration onto a new Master unit or to duplicate the current configuration to other Master units.

| Code    | Description   |
|---------|---|
| 1100000 | M1 Master unit - Screw terminal blocks                                |
| 1100002 | M1C Master unit - Clamp terminal blocks                               |
| 1100060 | MCM - Memory card   |
| 1100061 | MSC - Mosaic Safety Comunication connector                            |
| 1100099 | MSC-C - Mosaic Safety Comunication connector with<br>terminal end cap |
| 1100062 | USB configuration cable (A–mini B, length 1,8 m)                      |
| 1100079 | CPM - Polarizing keys for Mosaic connectors                           |





#### DIGITAL INPUTS 8

SAFETY OUTPUTS 4 single OSSD or 2 pairs

> EDM/RESTART 4

TEST OUTPUTS

STATUS OUTPUTS 4

LOGICAL OPERATORS 128

### APPROVALS

- 2006/42/EC: "Machine Directive"
- 2014/30/EU: "Electromagnetic Compatibility Directive".
- 2014/35/EU: "Low Voltage Directive"
- EN 61496-1:2013 (Type 4) "Safety of machinery Electro sensitive protective equipment - General requirements and tests"
- EN 61131-2:2007 "Programmable controllers Part 2. Equipment requirements and tests"
- EN 61508-1:2010 (SIL3) "Functional safety of electrical / electronic / programmable electronic safety related systems -General requirements"
- EN 61508-2:2010 (SIL3) "Functional safety of electrical / electronic / programmable electronic safety related systems -Requirements for electrical/electronic/programmable electronic safety-related systems"
- EN 61508-3:2010 (SIL3) "Functional safety of electrical / electronic / programmable electronic safety related systems: Software requirements"
- EN 61508-4:2010 (SIL3) "Functional safety of electrical / electronic / programmable electronic safety related systems -Definitions and abbreviations"
- IEC 62061:2005/A2:2015 (SILCL 3) "Safety of machinery -Functional safety of safety-related electrical, electronic and programmable electronic control systems"
- EN ISO 13849-1:2008 (Cat. 4 PL e) "Safety of machinery Safety-related parts of control systems - Part 1: General principles for design"
- IEC 61784-3:2008 "Industrial communication networks -Profiles - Part 3: Functional safety fieldbuses - General rules and profile definitions"
- UNI EN 81-20:2014 "Safety rules for the construction and installation of lifts. Lifts for the transport of persons and goods. Part 20: Passenger and goods passenger lift"
- UNI EN 81-50:2014 "Safety rules for the construction and installation of lifts. Examinations and test. Part 50: Design rules, calculations, examinations and tests of lift components"
- UL (C+US) mark for USA and Canada
- ANSI / UL 1998: "Safety Software in Programmable Components"

#### Certifications



### M1S

### ENHANCED MASTER UNIT

Master unit, also usable as a stand-alone device, able to control any other expansion unit. With 8 digital inputs, 4 single or 2 pairs OSSD safety outputs.

### APPLICATION EXAMPLE

The enhanced version of the master unit allows to control complex system and machinery that require a greater number of safety outputs, status outputs and logical operators

### TECHNICAL FEATURES

| Digital inputs        | 8 digital inputs  |
|-----------------------|---|
| Safety outputs        | 4 single OSSD or 2 pairs (PNP 400 mA output<br>current)                   |
| EDM                   | 4 inputs for Start/Restart interlock and external device monitoring (EDM) |
| Status outputs        | 4 programmable digital signal outputs<br>(PNP 100 mA output current)      |
| Test outputs          | 4 test outputs for sensor monitoring                                      |
| LED signalling        | Input/output status and fault diagnostics                                 |
| Configuration         | With PC via USB interface using MSD (Mosaic<br>Safety Designer) software  |
| MSC<br>bus connection | With MSC connector (optional)   |
| МСМ                   | Mosaic Configuration Memory (optional)                                    |

### ACCESSORIES

**MSC Rear Bus connector**: necessary to connect the Master unit to any expansion unit. As the Master unit can be used as stand-alone, the bus connector must be ordered separately.

MCM Card (Mosaic Configuration Memory): memory card designed to store the Master unit configuration as a backup. Can be used to restore the saved configuration onto a new Master unit or to duplicate the current configuration to other Master units.

| Code    | Description   |
|---------|---|
| 1100003 | M1S Master unit - Screw terminal blocks                               |
| 1100004 | M1SC Master unit - Clamp terminal blocks                              |
| 1100060 | MCM - Memory card   |
| 1100061 | MSC - Mosaic Safety Comunication connector                            |
| 1100099 | MSC-C - Mosaic Safety Comunication connector with<br>terminal end cap |
| 1100062 | USB configuration cable (A–mini B, length 1,8 m)                      |
| 1100079 | CPM - Polarizing keys for Mosaic connectors                           |

### MI8O2 - MI8O4

### **INPUT/OUTPUT EXPANSION UNITS**

Input/output expansion unit. With 8 digital inputs and 2 (MI8O2) or 4 (MI8O4) OSSD safety outputs. MI8O4 allows to configure the safety output as single channel.

### APPLICATION EXAMPLE

To provide more inputs and outputs for a smaller machinery connecting for example extra safety sensors and/or e-stops buttons and to control 2 extra actuators.



### TECHNICAL FEATURES

| Digital inputs               | 8 digital inputs   |
|------------------------------|--|
| Safety outputs               | 2 pairs OSSD (MI8O2) 4 single OSSD or 2 pairs<br>(MI8O4) (PNP 400 mA output current)           |
| EDM                          | 2 (MI8O2) or 4 (MI8O4) inputs for Start/Restart interlock and external device monitoring (EDM) |
| Status outputs               | 2 (MI8O2) or 4 (MI8O4) programmable digital<br>signal outputs (PNP 100 mA output current)      |
| Test outputs                 | 4 test outputs for sensor monitoring   |
| LED signalling               | Input/output status and fault diagnostics  |
| Connection to<br>Master Unit | Via MSC connector (included)   |

## PART NUMBERS

| Code    | Description                                   |
|---------|---|
| 1100010 | MI8O2 Expansion unit - Screw terminal blocks  |
| 1100110 | MI8O2C Expansion unit - Clamp terminal blocks |
| 1100011 | MI8O4 Expansion unit - Screw terminal blocks  |
| 1100111 | MI8O4C Expansion unit - Clamp terminal blocks |
| 1100079 | CPM - Polarizing keys for Mosaic connectors   |

### MI8 - MI16

### INPUT EXPANSION UNITS

Input expansion units with 8 (MI8) or 16 (MI16) digital inputs increase the number of inputs of an Master unit.

### APPLICATION EXAMPLE

To provide more inputs for a smaller machinery connecting for example extra safety sensors and/or e-stops buttons.

|                 | DIGITAL INPUTS<br>8 (MI8), 16 (MI16)<br>TEST OUTPUTS<br>4<br>COMPATIBILITY<br>M1 and M1S |
|-----------------|--|
| TECHNICAL FEATU | JRES   |

| Digital inputs               | 8 digital inputs                          |
|------------------------------|---|
| Test outputs                 | 4 test outputs for sensor monitoring      |
| LED signalling               | Input/output status and fault diagnostics |
| Connection to<br>Master Unit | Via MSC connector (included)              |

| Code    | Description                                  |
|---------|--|
| 1100020 | MI8 Expansion unit - Screw terminal blocks   |
| 1100120 | MI8C Expansion unit - Clamp terminal blocks  |
| 1100021 | MI16 Expansion unit - Screw terminal blocks  |
| 1100121 | MI16C Expansion unit - Clamp terminal blocks |
| 1100079 | CPM - Polarizing keys for Mosaic connectors  |





### MI12T8

### INPUT EXPANSION UNIT

Input expansion unit for safety mats and edges. With 12 digital inputs and 8 test outputs for sensor monitoring.

### APPLICATION EXAMPLE

With 8 test outputs can manage up to 4 independent safety mats or edges. Test output signals are used to monitor overloads and short circuits on input lines.



## TECHNICAL FEATURES

| Digital inputs               | 12 digital inputs                         |
|------------------------------|---|
| Test outputs                 | 8 test outputs for sensor monitoring      |
| LED signalling               | Input/output status and fault diagnostics |
| Connection to<br>Master Unit | Via MSC connector (included)              |



| Code    | Description                                    |
|---------|--|
| 1100022 | MI12T8 Expansion unit - Screw terminal blocks  |
| 1100122 | MI12T8C Expansion unit - Clamp terminal blocks |
| 1100079 | CPM - Polarizing keys for Mosaic connectors    |



## MA4 new

### ANALOGUE INPUTS EXPANSION UNIT

With 4 indipendent isolated analogue channels (500 V). Individual channels can be paired-up to allow sensor reading redundancy.

### APPLICATION EXAMPLE

Any application requiring analogic sensors connection as loading cells, pressure switches, temperature measurements, flow and level measurements, etc.



### TECHNICAL FEATURES

| Analogue inputs<br>detection    | Each channel can detect a 4-20 mA current<br>or a 0-10 V voltage (selectable via software) |
|---------------------------------|--|
| Analogue inputs<br>power supply | Each channel can supply 24V DC up to 30 mA   |
| LED signalling                  | Input status and fault diagnostics   |
| Connection to<br>Master Unit    | Via MSC connector (included)   |
| Resolution                      | 16 bit   |
| Sampling per<br>second          | 2,5 SPS 4000 SPS selectable  |
| Comparators                     | Semple with 1 or 2 thresholds  |

| Code    | Description                                 |
|---------|---|
| 1100025 | MA4 Expansion unit - Screw terminal blocks  |
| 1100125 | MA4C Expansion unit - Clamp terminal blocks |
| 1100079 | CPM - Polarizing keys for Mosaic connectors |

### MO4L HC S8 POWER

### HIGH CURRENT OUTPUT EXPANSION UNIT

Output expansion unit with 2 pairs OSSD or 4 single OSSD high current safety outputs (PNP 2,0 A per channel, 8 A in total), 4 relative inputs for external feedback contacts (EDM) and 8 status output.

### APPLICATION EXAMPLE

To provide 2 different high current output configurations (configurable with MSD configuration software)

- 4 single OSSD (1 safety output per channel with 4 feedback inputs)
- 2 pairs OSSD (2 safety output per channel with 2 feedback inputs)



### TECHNICAL FEATURES

| Safety outputs               | 4 single OSSD or 2 pairs<br>(PNP 2 A output current active high)               |
|------------------------------|--|
| EDM                          | 4 inputs for Start/Restart interlock and exter-<br>nal device monitoring (EDM) |
| Output current               | 2 A max per channel (total current 8 A)  |
| Status outputs               | 8 digital programmable signalling outputs -<br>(PNP 100 mA output current)     |
| LED signalling               | Output status and fault diagnostics  |
| Connection to<br>Master Unit | Via MSC connector (included)   |

## PART NUMBERS

| Code    | Description                                      |
|---------|--|
| 1100032 | MO4LHCS8 Expansion unit - Screw terminal blocks  |
| 1100132 | MO4LHCS8C Expansion unit - Clamp terminal blocks |
| 1100079 | CPM - Polarizing keys for Mosaic connectors      |

## MO4L 🔎

### OUTPUT EXPANSION UNIT

Output expansion unit with 2 pairs OSSD or 4 single OSSD safety outputs (PNP 400 mA), 4 relative inputs for external feedback contacts (EDM) and 4 status output.

### APPLICATION EXAMPLE

To provide 2 different output configurations (configurable with MSD configuration software)

- 4 single OSSD (1 safety output per channel with 4 feedback inputs)
- 2 pairs OSSD (2 safety output per channel with 2 feedback inputs)



## TECHNICAL FEATURES

| Safety outputs               | 4 single OSSD or 2 pairs<br>(PNP 400 mA output current active high)        |
|------------------------------|--|
| EDM                          | 4 inputs for Start/Restart interlock and external device monitoring (EDM)  |
| Status outputs               | 4 digital programmable signalling outputs -<br>(PNP 100 mA output current) |
| LED signalling               | Output status and fault diagnostics  |
| Connection to<br>Master Unit | Via MSC connector (included)   |

| Code    | Description                                    |
|---------|--|
| 1100012 | MO4L Expansion unit - Screw terminal blocks    |
| 1100212 | MO4LC - Expansion unit - Clamp terminal blocks |
| 1100079 | CPM - Polarizing keys for Mosaic connectors    |

## mosaic /

### MOR4

### SAFETY RELAY UNIT WITH CONFIGURABLE OUTPUTS

Output expansion unit with 4 configurable safety relays with guided contacts.

### APPLICATION EXAMPLE

To provide 4 configurable guided contact safety relays. It allows to select the safety category via MSD:

- Safety Cat. 1: 4 independent single channel outputs
- Safety Cat. 2: 4 independent single channel outputs with OTE (Output Test Equipment)
- Safety Cat. 4: 2 independent double channels outputs



## TECHNICAL FEATURES

| Safety relays                | 4 safety relays with 6 A 250 VAC guided contacts                               |
|------------------------------|--|
| EDM                          | 4 inputs for Start/Restart interlock and exter-<br>nal device monitoring (EDM) |
| LED signalling               | Output status and fault diagnostics  |
| Connection to<br>Master Unit | Via MSC connector (included). Do not use<br>Master OSSDs to drive relays       |

## PART NUMBERS

| Code    | Description                                  |
|---------|--|
| 1100042 | MOR4 Expansion unit - Screw terminal blocks  |
| 1100142 | MOR4C Expansion unit - Clamp terminal blocks |
| 1100079 | CPM - Polarizing keys for Mosaic connectors  |

### MOR4S8

### SAFETY RELAY WITH CONFIGURABLE OUTPUTS UNITS AND 8 STATUS OUTPUTS

Output expansion units provide 4 configurable safety relays with guided contacts.

## APPLICATION EXAMPLE

To provide 4 configurable guided contact safety relays. It allows to select the safety category via MSD:

- Safety Cat. 1: 4 independent single channel outputs
- Safety Cat. 2: 4 independent single channel outputs with OTE (Output Test Equipment)
- Safety Cat. 4: 2 independent double channels outputs



## TECHNICAL FEATURES

| Safety relays                | 4 safety relays with 6 A 250 VAC guided contacts                           |
|------------------------------|--|
| EDM                          | 4 inputs for Start/Restart interlock and external device monitoring (EDM)  |
| LED signalling               | Output status and fault diagnostics  |
| Status outputs               | 8 digital programmable signalling outputs -<br>(PNP 100 mA output current) |
| Connection to<br>Master Unit | Via MSC connector (included). Do not use<br>Master OSSDs to drive relays   |
| PART NUMBERS                 |  |

| Code    | Description                                    |
|---------|--|
| 1100043 | MOR4S8 Expansion unit - Screw terminal blocks  |
| 1100143 | MOR4S8C Expansion unit - Clamp terminal blocks |
| 1100079 | CPM - Polarizing keys for Mosaic connectors    |

### **MR2 - MR4**

### SAFETY RELAY UNITS

Output expansion units provide 2 (MR2) or 4 (MR4) safety relays outputs with guided contacts connectable to 2 or 4 independent OSSD pairs. These units can also be used separately from the Mosaic system.

### APPLICATION EXAMPLE

To provide 2 or 4 guided contact safety relay in applications where there is the need to cut the actuators power supply. Each NO contact is interrupted twice by the integrated safety relays.



### TECHNICAL FEATURES

| Safety relays                | MR2 - 2 safety relays with 6 A 250 VAC guided<br>contacts:<br>2 NO + 1 NC for EDM feedback<br>MR4 - 4 safety relays with 6 A 250 VAC guided<br>contacts: |
|------------------------------|--|
|                              | 4 NO + 2 NC for EDM feedback   |
| LED signalling               | OSSD output status (input in MRx)  |
| Connection to<br>Master Unit | The MR2 and MR4 expansion units do not<br>require MSC as they are wired directly to the<br>selected OSSD   |

## PART NUMBERS

| Code    | Description                                 |
|---------|---|
| 1100040 | MR2 Expansion unit - Screw terminal blocks  |
| 1100140 | MR2C Expansion unit - Clamp terminal blocks |
| 1100041 | MR4 Expansion unit - Screw terminal blocks  |
| 1100141 | MR4C Expansion unit - Clamp terminal blocks |
| 1100079 | CPM - Polarizing keys for Mosaic connectors |

### MO2 - MO4

### OUTPUT EXPANSION UNITS

Output expansion units with 2 (MO2) or 4 (MO4) safety outputs pairs increase the number of safety outputs of a Master unit.

### APPLICATION EXAMPLE

To provide more safety outputs in machine where different actuators need to be controlled. For example automatic packaging machines, etc.

| TECHNI                                  |   | SAFETY OUTPUTS<br>2 (MO2), 4 (MO4)<br>EDM/RESTART<br>2 (MO2), 4 (MO4)<br>STATUS OUTPUTS<br>2 (MO2), 4 (MO4)<br>COMPATIBILITY<br>M1 and M1S  |
|---|---|---|
| and the second                          |   | STATUS OUTPUTS  |
| 124 - 14                                | 1   | 2 (MO2), 4 (MO4)  |
| alle and                                |   |   |
| TECHNI                                  | CAL FEATU   | IRES  |
|   | MO2 - 2 OSSD p  | pairs (PNP 400 mA output current)   |
| Safety outputs                          | MO2 - 2 OSSD p  |   |
|   | MO2 - 2 OSSD p<br>MO4 - 4 OSSD p<br>MO2 - 2 inputs<br>external device<br>MO4 - 4 inputs   | pairs (PNP 400 mA output current)   |
| Safety outputs                          | MO2 - 2 OSSD p<br>MO4 - 4 OSSD p<br>MO2 - 2 inputs<br>external device<br>MO4 - 4 inputs<br>external device<br>MO2 - 2 progra<br>(PNP 100 mA c                   | pairs (PNP 400 mA output current)<br>pairs (PNP 400 mA output current)<br>for Start/Restart interlock and<br>e monitoring (EDM)<br>for Start/Restart interlock and<br>e monitoring (EDM)<br>ammable digital signal outputs -<br>putput current)<br>ammable digital signal outputs -   |
| Safety outputs<br>EDM                   | MO2 - 2 OSSD p<br>MO4 - 4 OSSD p<br>MO2 - 2 inputs<br>external device<br>MO4 - 4 inputs<br>external device<br>MO2 - 2 progra<br>(PNP 100 mA c<br>MO4 - 4 progra | pairs (PNP 400 mA output current)<br>pairs (PNP 400 mA output current)<br>for Start/Restart interlock and<br>e monitoring (EDM)<br>for Start/Restart interlock and<br>e monitoring (EDM)<br>ammable digital signal outputs -<br>putput current)<br>ammable digital signal outputs -   |
| Safety outputs<br>EDM<br>Status outputs | MO2 - 2 OSSD p<br>MO4 - 4 OSSD p<br>MO2 - 2 inputs<br>external device<br>MO4 - 4 inputs<br>external device<br>MO2 - 2 progra<br>(PNP 100 mA c<br>MO4 - 4 progra | pairs (PNP 400 mA output current)<br>pairs (PNP 400 mA output current)<br>for Start/Restart interlock and<br>e monitoring (EDM)<br>for Start/Restart interlock and<br>e monitoring (EDM)<br>ammable digital signal outputs -<br>poutput current)<br>ammable digital signal outputs -<br>poutput current)<br>tatus and fault diagnostics |

| Code    | Description                                 |
|---------|---|
| 1100030 | MO2 Expansion unit - Screw terminal blocks  |
| 1100130 | MO2C Expansion unit - Clamp terminal blocks |
| 1100031 | MO4 Expansion unit - Screw terminal blocks  |
| 1100131 | MO4C Expansion unit - Clamp terminal blocks |
| 1100079 | CPM - Polarizing keys for Mosaic connectors |





RJ-45 (1 for MV1, 2 for MV2) connectors for encoders and terminal blocks for proximity switches.

Max. input frequency for encoders: up to 500 KHz (300 KHz for HTL encoder).

Max. input frequency for proximity switches: up to 5 KHz.

The MV2 module includes two configurable logical outputs and is therefore able to control up to two independent axis (configuration via MSD).



### MV0 - MV1 - MV2

### SAFETY SPEED MONITORING UNITS

Safety speed monitoring (up to PL e) for: zero speed control, max. speed, speed range and direction control.

### APPLICATION EXAMPLE

Any application requiring speed monitoring for a hazardous tool. See relevant application example onpage 40. Maintenance speed control in rail dependent storage and retrieval equipment applications.

### TECHNICAL FEATURES

| Digital inputs               | MV0 - Input for 2 PNP/NPN proximity switches<br>MV1 - Input for 1 incremental encoder (TTL,<br>HTL or SIN/COS) and 1 or 2 PNP/NPN proximi-<br>ty switches<br>MV2 - Input for 1 or 2 incremental encoder<br>(TTL, HTL o SIN/COS) and 1 or 2 PNP/NPN<br>proximity switches |
|------------------------------|--|
| Speed thresholds             | Up to 8 logically selectable speed thresholds<br>(freely configurable via MSD) for each logical<br>output (axis)   |
| LED signalling               | Input/output status and fault diagnostics  |
| Connection to<br>Master Unit | Via MSC connector (included)   |

## ACCESSORIES

**SAFECODER** - Safety Sin/Cos incremental encoder. See page15

MCCV - Speed monitoring sniffer cable. See page 20

| Code    | Description   |
|---------|---|
| 1100077 | MV0 - Proximities switch expansion module   |
| 1100070 | MV1T - 1 TTL incremental encoder + 1 or 2 PNP/NPN proximity switches expansion module                       |
| 1100086 | MV1TB - 1 TTL incremental encoder (24 VDC) + 1 or 2 PNP/NPN proximity switches expansion module             |
| 1100071 | MV1H - 1 HTL incremental encoder + 1 or<br>2 PNP/NPN proximity switches expansion module                    |
| 1100072 | MV1S - 1 SIN/COS incremental encoder + 1 or<br>2 PNP/NPN proximity switches expansion module                |
| 1100073 | MV2T - 1 or 2 TTL incremental encoders + 1 or<br>2 PNP/NPN proximity switches expansion module              |
| 1100087 | MV2TB - 1 or 2 TTL incremental encoders (24 VDC)<br>+ 1 or 2 PNP/NPN proximity switches expansion<br>module |
| 1100074 | MV2H - 1 or 2 HTL incremental encoders + 1 or 2<br>PNP/NPN proximity switches expansion module              |
| 1100076 | MV2S - 1 or 2 SIN/COS incremental encoders + 1 or 2 PNP/NPN proximity switches expansion module             |
| 1100079 | CPM - Polarizing keys for Mosaic controller<br>connectors   |

### MCT1 - MCT2

### REMOTE INTERFACE UNITS

Interface module allowing the connection of remote expansions units via the MSC bus.

### APPLICATION EXAMPLE

Ideal solution for the interconnection of the safety functions of more machineries on a single production line.



### TECHNICAL FEATURES

| Connections                  | MCT1 - 1 connection: 1 input or 1 output to be<br>placed at the beginning or at the end of the<br>network   |
|------------------------------|---|
|                              | MCT2 - 2 connections: 1 input and 1 output  |
| Cable                        | Shielded RS 485 serial interface compatible<br>cable (4 wires + shield) via the connector block.<br>We recommend the use of ReeR's MCTx cables<br>for a correct operation of the system |
| Total distance               | Up to 50 m for each connection<br>(total distance up to 250 m).<br>Max. 5 MCT expansions units  |
| LED signalling               | Module status and fault diagnostics   |
| Connection to<br>Master Unit | Via MSC connector (included)  |

## PART NUMBERS

| Code    | Description                                      |
|---------|--|
| 1100058 | MCT1 Expansion unit                              |
| 1100057 | MCT2 Expansion unit                              |
| 1100063 | MCT25 - Serial cable for MSC bus transfer 25 m   |
| 1100064 | MCT50 - Serial cable for MSC bus transfer 50 m   |
| 1100065 | MCT100 - Serial cable for MSC bus transfer 100 m |

## HM1

### DISPLAY UNIT

Alphanumeric display. It displays the messages programmed using the HSD software.



## APPLICATION EXAMPLE

Used in control panels to display status messages as diagnostic or operation functions of the safety system. Can be also used to display other functioning messages of the machine or the plant.

| TECHNICAL FEATURES      |  |  |
|-------------------------|--|--|
| Display                 | Green display LCD 2x16   |  |
| Ports                   | 2 configurable RS 485 serial ports USB port for messages on display programming  |  |
| Inputs                  | 4 inputs for the connection with Mosaic:<br>2 synchronous serial ports (clock + data) or 4<br>asynchronous serial ports (data) |  |
|                         | HM1 can be connected to Mosaic in 3 ways:  |  |
|                         | Wired to a status output connected to the serial operator, asynchronous serial connection Max 32 status displayed.             |  |
|                         |  |  |
| Connection<br>to Master | Wired to 2 status outputs connected to the serial operator, synchronous serial connection Max 16 status displayed.             |  |
|                         |  |  |
|                         | Wired to the serial MBx module via RS 485 serial port, all I/O statuses and diagnostic displayed.                              |  |
| PART NUMBERS            |  |  |

| Code    | Description                      |
|---------|----------------------------------|
| 1100090 | HM1 Expansion unit               |
| 1100062 | USB cable A–mini B, length 1,8 m |

## MOSAL

### **MBx**

### FIELD-BUS INTERFACE UNITS

Expansion unit for connection to the most common industrial Field-bus systems for diagnostics and data communication.

### APPLICATION EXAMPLE

In all applications where it is required to communicate between the machine's safety system and the PLC control.



MBD - DeviceNET MBC - CANopen **MBEC** - EtherCAT MBEI - Ethernet IP **MBEP** - PROFINET MBU - Universal Serial Bus MBMR - ModBus RTU MBEM - ModBus TCP MBCCL - CC-Link

> COMPATIBILITY M1 and M1S

### TECHNICAL FEATURES

| Ports |  |  |
|-------|--|--|
|       |  |  |

RS 485 serial ports for I/O Bus expansion USB port for configuration

Connection to Via MSC connector (included) Master Unit

## PART NUMBERS

| Code    | Description                               |
|---------|---|
| 1100050 | MBP Profibus DP expansion module          |
| 1100051 | MBD DeviceNET expansion module            |
| 1100052 | MBC CANopen expansion module              |
| 1100053 | MBEC EtherCAT expansion module *          |
| 1100054 | MBEI EtherNET/IP expansion module *       |
| 1100055 | MBEP PROFINET expansion module            |
| 1100056 | MBU Universal Serial Bus expansion module |
| 1100059 | MBCCL CC-link expansion module *          |
| 1100082 | MBMR Modbus RTU expansion module          |
| 1100083 | MBEM Modbus TCP expansion module *        |

\* All Ethernet modules have a double RJ45 port

### **MOS8 - MOS16**

### STATUS OUTPUTS EXPANSION UNITS

Status outputs expansion units for the automation process with safety level: SIL 1 - SILCL 1 - PL c - Cat. 1

## APPLICATION EXAMPLE

Modules for automation process where status outputs are required. With these units, Mosaic controller can also be used as a PLC for automation.

| ТЕСНИК                       | SAFETYLEVEL<br>SIL 1<br>SIL 2<br>SIL 1-SILCL 1<br>PL - GAL 1<br>STATUS OUTPUTS<br>8 (MOS8)<br>16 (MOS16)<br>COMPATIBILITY<br>M1 and M1S |  |
|------------------------------|---|--|
| Status outputs               | MOS8 - 8 programmable digital status<br>outputs (PNP 100 mA output current)   |  |
| Status outputs               | MOS16 - 16 programmable digital status<br>outputs (PNP 100 mA output current)   |  |
| LED signalling               | Output status and fault diagnostics   |  |
| Connection to<br>Master Unit | Via MSC connector (included)  |  |
|                              |   |  |



| Code    | Description          |
|---------|----------------------|
| 1100091 | MOS8 Expansion unit  |
| 1100092 | MOS16 Expansion unit |

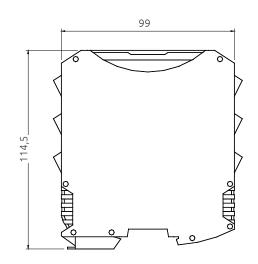


## **TECHNICAL FEATURES SUMMARY**

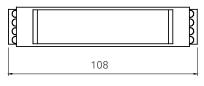
## MAXIMUM SYSTEM CAPABILITIES: M1 VS M1S



| Main unit  | M1  | M1S | Note   |
|--|-----|-----|--|
| Maximum number of expansion units                        | 14  | 14  |  |
| USB port   | yes | yes |  |
| MCM card slot  | yes | yes |  |
| Connection with MSC bus                                  | yes | yes |  |
| MSC connector provided                                   | NO  | NO  |  |
| Digital inputs   | 128 | 128 |  |
| Start/Restart inputs and External<br>Device Monitoring   | 16  | 32  |  |
| Fieldbus input   | 8   | 32  | The M1S main unit uses a new "footprint map" for data exchange with the fieldbus units   |
| Analogue inputs  | -   | 16  | M1S system only  |
| Safety outputs (OSSD)                                    | 16  | 32  | The M1S main unit provides 4 single (or 2 pairs) OSSD safety outputs   |
| Programmable status outputs                              | 32  | 48  | The status outputs of the M1S main unit, MI8O4 and MO4L expansion units car<br>be converted to feedback inputs (up to 4 feedback inputs for the 4 single OSSD<br>safety outputs) |
|  |     |     | The status outputs of the MOS8 and MOS16 expansion units can reach the safety level: SIL 1 - SILCL 1 - PL c - Cat. 1.  |
| Maximum number of operators managed by the MSD sosftware | 64  | 128 |  |
| Maximum number of managed timers                         | 32  | 48  |  |
| Maximum number of "Muting" operators                     | 4   | 8   |  |
| Maximum number of operators<br>"Safety Guard Lock"       | 4   | 8   |  |
| Maximum number of<br>"Fieldbus Probe" outputs            | 16  | 32  |  |



"Fieldbus Probe" outputs



Dimensioni in mm

| 22,5   |
|--------|
| 0000   |
| 0000   |
|        |
|        |
|        |
| i) III |

### MECHANICAL CHARACTERISTICS

- Compact design: single module dimensions 22.5 x 99 x 114.5 mm
- ReeR MSC rear bus connector for connection with other expansion modules
- Operating temperature: -10 ... +55 °C
- Storage temperature: -20 ... +85 °C
- Protection rating: IP20 for housing, IP 2X for terminal block
- Rail fastening according to EN 50022-35 standard
- Removable terminal blocks with screw or clamp contacts (24 x 22.5 mm)





Clamp contacts



## EXPANSION UNITS TECHNICAL FEATURES

| Input<br>-<br>yes<br>yes<br>3 - 16<br>- | -<br>-<br>yes<br>yes                        | Ana-<br>logue<br>input<br>unit<br>-<br>yes<br>yes<br>.CL 3 accor<br>-<br>8 | Output<br>units<br>-<br>yes<br>yes<br>rding to IEC<br>-<br>-<br>2 pairs<br>(MO2)<br>4 pairs<br>(MO4)<br>PNP<br>400 mA<br>2 (MO2)<br>4 (MO4) | High<br>Current<br>Safety<br>Outputs<br>units<br>-<br>-<br>yes<br>yes<br>C 61508 - IEC 6<br>-<br>-<br>4 single or<br>2 pairs<br>PNP<br>2 A max | Safety<br>Outputs<br>units<br>-<br>yes<br>2061 / PL e –<br>-<br>-<br>-<br>4 single or<br>2 pairs<br>PNP<br>400 mA<br>max | Guided<br>contact<br>relay<br>output<br>units<br>-<br>-<br>-<br>Cat. 4 accor<br>-<br>-<br>- | Remote<br>interface<br>units<br>-<br>yes<br>yes<br>ding to ISO<br>-<br>- | Safety relay<br>configurable<br>output units<br>-<br>yes<br>yes<br>13849-1<br>-<br>-   | Safety<br>speed<br>monito-<br>ring units<br>-<br>yes<br>yes<br>2 - 4<br>-   | Automa-<br>tion units   | Field<br>bus<br>units<br>yes<br>yes<br>-<br>-<br>-  |
|---|---|--|---|--|--|---|--|--|---|---|---|
| -<br>yes<br>yes                         | -<br>yes<br>yes<br>SIL 3 – SIL<br>12        | -<br>yes<br>yes<br>.CL 3 accor   | -<br>yes<br>yes<br>rding to IEC<br>-<br>-<br>2 pairs<br>(MO2)<br>4 pairs<br>(MO4)<br>PNP<br>400 mA<br>2 (MO2)                               | -<br>yes<br>C 61508 - IEC 6<br>-<br>-<br>4 single or<br>2 pairs<br>PNP<br>2 A max  | -<br>yes<br>2061 / PL e –<br>-<br>-<br>4 single or<br>2 pairs<br>PNP<br>400 mA   | -<br>-<br>· Cat. 4 accor<br>-   | -<br>yes<br>yes<br>rding to ISO<br>-                                     | -<br>yes<br>yes<br>13849-1<br>-  | -<br>yes<br>yes<br>2 - 4  | -<br>yes<br>yes<br>-  | yes<br>yes  |
| yes<br>yes<br>3 - 16                    | yes<br>yes<br>SIL 3 – SIL<br>12             | yes<br>yes<br>-CL 3 accor<br>-   | yes<br>yes<br>rding to IEC<br>-<br>-<br>2 pairs<br>(MO2)<br>4 pairs<br>(MO4)<br>PNP<br>400 mA<br>2 (MO2)                                    | yes<br>yes<br>C 61508 - IEC 6<br>-<br>-<br>4 single or<br>2 pairs<br>PNP<br>2 A max  | yes<br>yes<br>2061 / PL e –<br>-<br>-<br>4 single or<br>2 pairs<br>PNP<br>400 mA   | -<br>-<br>Cat. 4 accor<br>-   | yes<br>yes<br>ding to ISO<br>-   | yes<br>yes<br>13849-1<br>-   | yes<br>yes<br>2 - 4   | yes<br>yes<br>-<br>-  | yes<br>yes<br>-   |
| yes<br>3 - 16                           | yes<br>SIL 3 – SIL<br>12                    | yes<br>-CL 3 accor<br>-  | yes<br>rding to IEC<br>-<br>-<br>2 pairs<br>(MO2)<br>4 pairs<br>(MO4)<br>PNP<br>400 mA<br>2 (MO2)   | yes<br>C 61508 - IEC 6<br>-<br>4 single or<br>2 pairs<br>PNP<br>2 A max  | yes<br>2061 / PL e –<br>-<br>-<br>4 single or<br>2 pairs<br>PNP<br>400 mA  | -<br>• Cat. 4 accor<br>-  | yes<br>rding to ISO<br>-   | yes<br>13849-1<br>-  | yes<br>2 - 4  | yes<br>-<br>-   | yes<br>-  |
| 3 - 16                                  | SIL 3 – SIL<br>12                           | -CL 3 accor  | 2 pairs<br>(MO2)<br>4 pairs<br>(MO4)<br>PNP<br>400 mA<br>2 (MO2)  | 4 single or<br>2 pairs<br>PNP<br>2 A max   | 2061 / PL e –<br>-<br>-<br>4 single or<br>2 pairs<br>PNP<br>400 mA   | Cat. 4 accor<br>-   | ding to ISO<br>-   | -  | 2 - 4   | -   | -   |
| 3 - 16                                  | 12  | -  | -<br>2 pairs<br>(MO2)<br>4 pairs<br>(MO4)<br>PNP<br>400 mA<br>2 (MO2)   | -<br>4 single or<br>2 pairs<br>PNP<br>2 A max  | -<br>4 single or<br>2 pairs<br>PNP<br>400 mA   | -   | -  | -  |   | -   |   |
|   |   | - 8  | 2 pairs<br>(MO2)<br>4 pairs<br>(MO4)<br>PNP<br>400 mA<br>2 (MO2)  | 4 single or<br>2 pairs<br>PNP<br>2 A max   | -<br>4 single or<br>2 pairs<br>PNP<br>400 mA   | -   | -  |  |   |   | -   |
| -                                       |   | -  | 2 pairs<br>(MO2)<br>4 pairs<br>(MO4)<br>PNP<br>400 mA<br>2 (MO2)  | 4 single or<br>2 pairs<br>PNP<br>2 A max   | 4 single or<br>2 pairs<br>PNP<br>400 mA  | -   | -  | -  | -   | <u>.</u>  | -   |
| -                                       |   | -  | (MO2)<br>4 pairs<br>(MO4)<br>PNP<br>400 mA<br>2 (MO2)   | 2 pairs<br>PNP<br>2 A max  | 2 pairs<br>PNP<br>400 mA   |   | -  | -  | -   | -   | -   |
|   | -   |  |   | 8  |  |   |  |  |   |   |   |
| -                                       |   | -  | 4 (MO4)<br>PNP<br>100 mA  | PNP<br>100 mA  | 4<br>PNP<br>100 mA   | -   | -  | MOR4S8<br>8 PNP<br>100 mA  | -   | 8 - 16<br>PNP<br>100 mA<br>(Note)   | -   |
| 4                                       | 8   |  | -   | -  |  | -   | -  | -  | -   | -   | -   |
| -                                       | -   |  | -   | -  | -  | 2 NO +<br>1 NC<br>4 NO +<br>2 NC<br>6 A 250<br>VAC  | -  | 4 NO single<br>6 A 250 VAC<br>or<br>2 NO pairs<br>6 A 250 VAC  | -   | -   | -   |
| -                                       | -   |  | 2 (MO2)<br>4 (MO4)  | 4  | 4  | -   | -  | 4  | -   | -   | -   |
| tput sta                                | atus and f                                  | ault diagr   | nostics   |  |  | Output stat   | US   |  | Input<br>status and<br>fault diag.  | Output<br>status and<br>fault diag.   | Fault<br>diag.  |
|   |   |  |   |  | 24 ± 2   | 20%   |  |  |   |   |   |
|   |   |  | R   | emovable ter   | minal blocks   | s, screw or cl  | amp contact  | S  |   |   |   |
|   |   |  |   |  |  |   |  |  |   |   |   |
|   |   |  |   |  | -20 +  | 85 °C   |  |  |   |   |   |
|   | IP20 for housing / IP 2X for terminal block |  |   |  |  |   |  |  |   |   |   |
|   |   |  |   | Rail fastening according to EN 50022-35 standard   |  |   |  |  |   |   |   |
|   |   |  |   | R  | IP20 for h   | Removable terminal blocks<br>-10 +<br>-20 +<br>IP20 for housing / IP 2                      | -10 +55 °C<br>-20 +85 °C<br>IP20 for housing / IP 2X for termin          | Removable terminal blocks, screw or clamp contact<br>-10 +55 °C<br>-20 +85 °C<br>IP20 for housing / IP 2X for terminal block | Removable terminal blocks, screw or clamp contacts<br>-10 +55 °C<br>-20 +85 °C<br>IP20 for housing / IP 2X for terminal block | 24 ± 20%<br>Removable terminal blocks, screw or clamp contacts<br>-10 +55 °C<br>-20 +85 °C<br>IP20 for housing / IP 2X for terminal block | 24 ± 20%<br>Removable terminal blocks, screw or clamp contacts<br>-10 +55 °C<br>-20 +85 °C<br>IP20 for housing / IP 2X for terminal block |

NOTE: The status outputs of the MOS8 and MOS16 expansion units can reach the safety level: SIL 1 - SILCL 1 - PL c - Cat. 1





Shaft version



Hollow shaft version

### APPROVALS

- 2006/42/EC "Machinery Directive"
- 2004/108/EC "Electromagnetic Compatibility (EMC)"
- EN ISO 13849-1 "Safety of machinery: Safety-related parts of control systems. Part 1: General principles for design"
- EN ISO 13849-2 "Safety of machinery: Safety-related parts of control systems. Part 2: Validation"
- IEC 61508 "Functional safety of electrical, electronic and programmable electronic safety-related systems
- EN ISO 61800-5-2 "Adjustable speed electrical power drive systems". Part 5-2 Safety requirements Functional
- UL (C+US) mark for USA and Canada
- BGIA Institute for Occupational Safety and Health Germany

#### Certifications



## SALEDDER

Safety Sin/Cos incremental encoder. Together with Mosaic, it forms a SIL 3 certified safety function for speed monitoring. Available in two models: Shaft or Hollow shaft.

### APPLICATION EXAMPLE

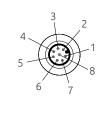
Any applications requiring speed monitoring of a rotating axis. See the application example on page 34.

Features a robust and reliable interface and the ability to handle high mechanical loads.

### **TECHNICAL FEATURES**

| Shaft typeHollow shaft version Ø 12 mmShaft version Ø 10 mm with flat surface |  |
|---|--|
| Fastening   | Safety-Lock™<br>Allow high rotational speed and high shaft load<br>capacity                    |
| Protection<br>rate  | Housing and flange side IP67, shaft IP65 (optional<br>IP67)                                    |
| Immunity to interference  | Shock and vibration resistant<br>Insensitive to strong magnetic fields                         |
| Resolution  | 2048 pulse rate  |
| Power supply  | SC3 24D2048R - 24 VDC<br>SC3 05D2048R - 5 VDC<br>SC3 24B2048R - 24 VDC<br>SC3 05B2048R - 5 VDC |
| Connector   | Radial M12 8-pole  |





#### M12 8-pole

1 - GND 2 - + V 3 - A: Sine output 4 - Ā: Sine output 5 - B: Cosine output 6 - B: Cosine output 7 - N.C. 8 - N.C. shield - PE

| Code    | Description  |
|---------|--|
| 1100102 | SC3 24D2048R - 24 V Hollow Shaft version Ø 12 mm               |
| 1100103 | SC3 05D2048R - 5 V Hollow Shaft version Ø 12 mm                |
| 1100104 | SC3 24B2048R - 24 V Shaft version Ø 10 mm with flat<br>surface |
| 1100105 | SC3 05B2048R - 5 V Shaft version Ø 10 mm with flat<br>surface  |

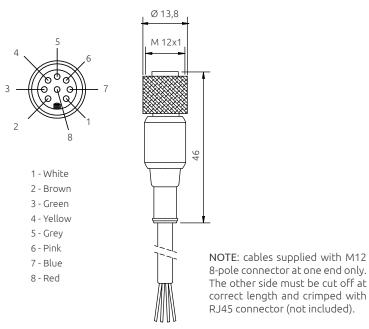


## CABLES NEEDED

### C8D x SH

#### M12 straight connector, 8 poles, shielded cable

| Model     | Code    | Description                   |
|-----------|---------|-------------------------------|
| C8D 5 SH  | 1330930 | Pre-wired shielded cable 5 m  |
| C8D 10 SH | 1330931 | Pre-wired shielded cable 10 m |
| C8D 15 SH | 1330932 | Pre-wired shielded cable 15 m |

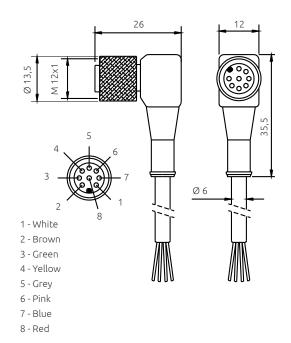


surface

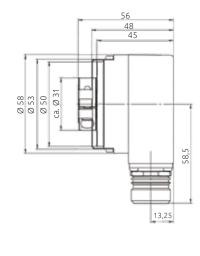
### C8D 9x SH

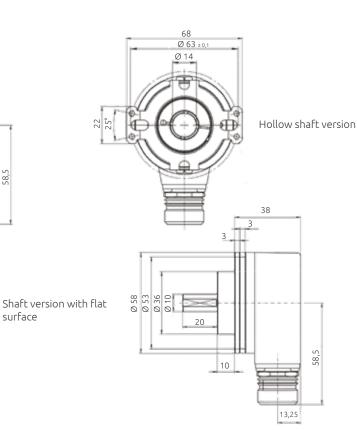
#### M12 90° angled connector, 8 poles, shielded cable

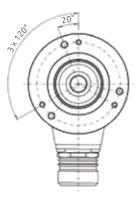
| Model      | Code    | Description                   |
|------------|---------|-------------------------------|
| C8D 95 SH  | 1330933 | Pre-wired shielded cable 5 m  |
| C8D 910 SH | 1330934 | Pre-wired shielded cable 10 m |
| C8D 915 SH | 1330935 | Pre-wired shielded cable 15 m |



### MECHANICAL DATA

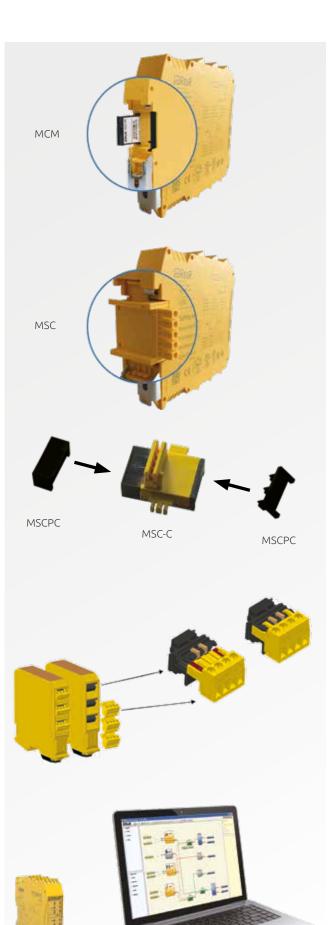






Dimensions: mm

## MOSAIC )



### MCM

### MOSAIC CONFIGURATION MEMORY

| Models | Ordering codes | Description                               |
|--------|----------------|---|
| MCM    | 1100060        | Mosaic Configuration Memory – Memory Card |

### MSC

### MOSAIC SAFETY COMMUNICATION

| Models | Ordering codes | Description   |
|--------|----------------|---|
| MSC    | 1100061        | Mosaic Safety Communication – Connector                                   |
| MSC-C  | 1100099        | Mosaic Safety Communication – Connector with<br>terminal end caps (MSCPC) |
| MSCPC  | 1100095        | Set of 10 Mosaic terminal end caps  |

### **CPM** POLARIZING KEYS

| Models | Ordering codes | Description                                      |
|--------|----------------|--|
| CPM    | 1100079        | Polarizing keys for Mosaic controller connectors |

### **CSU** CONFIGURATION CABLE

| Models | Ordering codes | Description                        |
|--------|----------------|------------------------------------|
| CSU    | 1100062        | USB A cable – Mini B, lenght 1,8 m |





### MTB

### SET OF SCREW TERMINAL BLOCKS

| Models  | Ordering codes | Description                                      |
|---------|----------------|--|
| MTB - Y | 1100044        | Set of 6 numbered screw terminal blocks (yellow) |
| MTB - B | 1100045        | Set of 6 numbered screw terminal blocks (black)  |

MTBC

### SET OF CLAMP TERMINAL BLOCKS

| Models   | Ordering codes | Description                                      |  |  |
|----------|----------------|--|--|--|
| MTBC - Y | 1100046        | Set of 6 numbered clamp terminal blocks (yellow) |  |  |
| MTBC - B | 1100047        | Set of 6 numbered clamp terminal blocks (black)  |  |  |

### MCT

### SERIAL CABLE FOR MSC BUS TRANSFER

| Models | Ordering codes | Description                                 |
|--------|----------------|---|
| MC10   | 1100113        | MCT serial cable for MSC bus transfer 10 m  |
| MC25   | 1100063        | MCT serial cable for MSC bus transfer 25 m  |
| MC50   | 1100064        | MCT serial cable for MSC bus transfer 50 m  |
| MC100  | 1100065        | MCT serial cable for MSC bus transfer 100 m |

### MPD

### PULL-DOWN ADAPTER

| Models                       | Ordering codes | Description        |  |
|------------------------------|----------------|--------------------|--|
| MPD                          | 1350150        | Pull-down resistor |  |
| Each kit contains 2 adapters |                |                    |  |

### MCCV

### SNIFFER CABLE

| Models          | Ordering codes | Description   |
|-----------------|----------------|---|
| MCCV 15P 3F 1.0 | 1100069        | Sniffer Cable (splitter D-Sub 15-pole / RJ45)<br>1000 mm for safety speed monitoring MV modules |
| MCCV 15P 3F 1.4 | 1100067        | Sniffer Cable (splitter D-Sub 15-pole / RJ45)<br>1400 mm for safety speed monitoring MV modules |
| MCCV 15P 3F 1.8 | 1100048        | Sniffer Cable (splitter D-Sub 15-pole / RJ45)<br>1800 mm for safety speed monitoring MV modules |
| MCCV 25P 2F 2.5 | 1100068        | Sniffer Cable (splitter D-Sub 25-pole / RJ45)<br>2500 mm for safety speed monitoring MV modules |

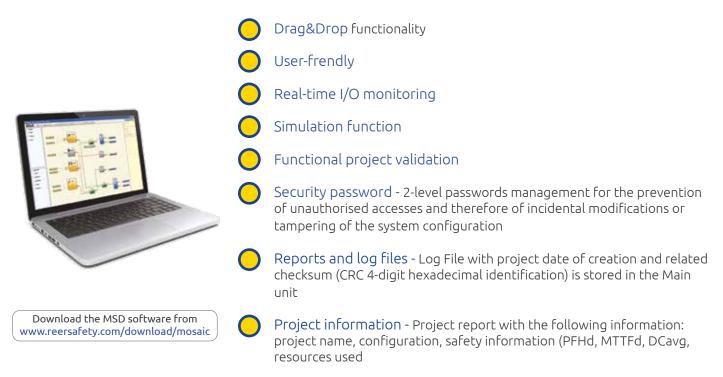


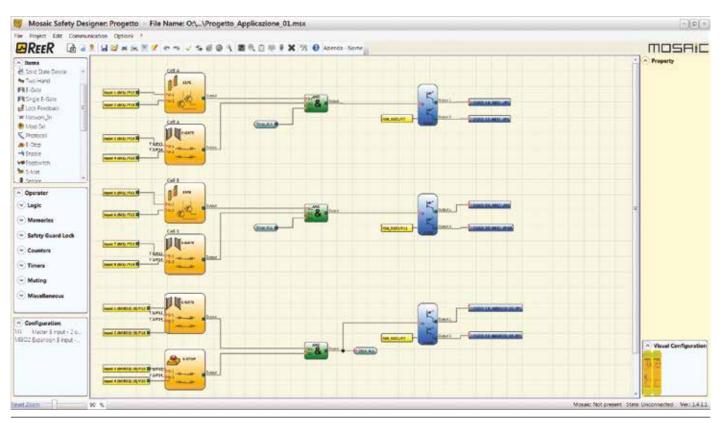
### **CONFIGURATION SOFTWARE**

MOSAL

Every Master Unit comes with a complementary copy of the MSD designer software. The Master Unit configuration is done via USB connection.







MSD configuration software desktop.

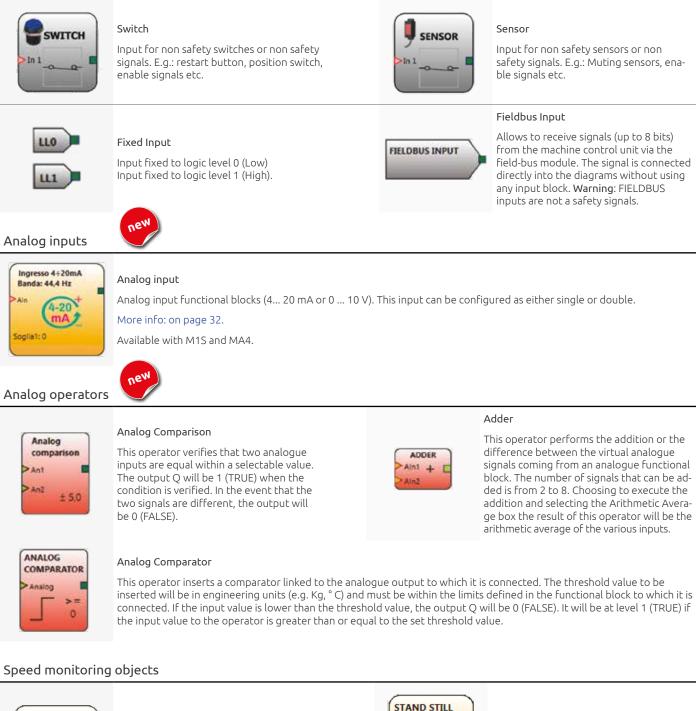
Mosaic Safety Designer MSD



#### Input objects



#### Input objects





Stand Still

Check that the speed is zero or not greater than the values set.



#### Stand Still and Speed Control

Check that the speed does not exceed the values set for both the max. speed and zero speed.





Check that the speed is not greater than the values set.

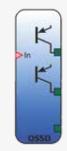


#### Window Speed Control

Check that the speed is not lower or higher than the values set.



#### Output objects



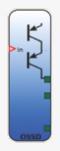
#### OSSD (safety outputs)

PNP safety static outputs (dual channel, 400 mA). The 2 outputs cannot operate independently.



#### Relay

The Output relay is a NO relay output. Relay outputs are closed when the input is equal to 1 (TRUE), otherwise they are open (FALSE).



#### Single OSSD (safety outputs)

PNP safety static outputs (single channel, 400 mA). The outputs can operate independently.

Available with M1S, MI8O4 and MO4LHCS8 units.



#### Status (signal output)

PNP static outputs (single channel, 100 mA). Can be connected to any point in the project.

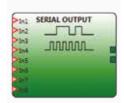
#### Serial Output



#### Fieldbus Probe Output

Allows to send signals (up to 16 bits) to the machine control unit via the field-bus module.

The signal is connected directly into the diagrams without using any output block.



It makes possible the transmission of information status to a PLC or HM1 without the need to use fieldbus modules. The Serial Output operator outputs the status of up to 8 inputs, serializing the information. Max. number of operators: 4 - total 32 information status.

The serial line can be: Synchronous (1 clock + 1 data output) Asynchronous (1 Manchester coding data output). For a tipical application sample, see HM1 on page 14.

#### Comments



#### Comments and Title

Add comments to your projects and sign it with a dedicated title box.

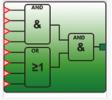
#### Interpage operator





#### Logical operators - Up to 64 (M1) or 128 (M1S) logical operator can be used

| Int &           | AND<br>Logical AND returns an output of 1 (TRUE)<br>if all the inputs are 1 (TRUE).  | NAND<br>In1 & | NAND<br>Logical NAND returns an output of 0 (FAL-<br>SE) if all the inputs are 1 (TRUE).  |
|-----------------|--|---------------|---|
| > NOT           | NOT<br>Logical NOT inverts the logical status of<br>the input.   |               | OR<br>Logical OR returns an output of 1 (TRUE) if<br>at least one of the inputs is 1 (TRUE).  |
| NOR<br>121      | NOR<br>Logical NOR returns an output of 0 (FALSE)<br>if at least one of the inputs is 1 (TRUE).                                  |               | XOR<br>Logical XOR returns an output 0 (FALSE) if<br>the input's number at 1 (TRUE) is even or<br>the inputs are all 0 (FALSE).   |
| xnor<br>tela1=1 | XNOR<br>Logical XNOR returns an output 1 (TRUE)<br>if the input's number at 1 (TRUE) is even or<br>the inputs are all 0 (FALSE). | MULTIPLEXER   | MultiplexerLogical Multiplexer forwards the signal of<br>the inputs to the output according to the<br>SEL selection. If the SEL1+SEL4 have only<br>one bit set, the selected In n is<br>connected to the Output.If the SEL inputs are:<br>more than one = 1 TRUE)<br>none = 1 (TRUE). |
|                 |  |               | The output is set to 0 (FALSE) independently from the In n values.  |



#### Logical Macro

Groupings can be created with a maximum of three operators of different types for a total of max. 8 inputs. This allows to increase the maximum number of operators used.

#### Memory operators



#### D Flip-Flop

The D Flip-Flop operator saves the previously set status on output Q.



#### SR Flip-Flop

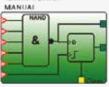
SR Flip-Flop operator brings output Q at 1 with Set, 0 with Reset.



#### T Flip-Flop

This operator switches the Q output at each rising edge of the T input (Toggle).

MACRO RESTART



#### Macro Restart Manual

Used to combine a logic gate chosen by the user with the Restart Manual functional block User Restart Manual.



#### User Restart Manual

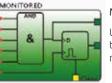
The User Restart Manual operator saves the restart signal according to the Inputs: In, Rising edge input and Clear.



#### User Restart Monitored

The User Restart Monitored operator is used to save the restart signal according to the inputs.





#### Macro Restart Monitored

Used to combine a logic gate chosen by the user with the Restart Manual functional block User Restart Monitored.



#### Timer operators

|   | Monostable<br>The Monostabile operator generates a<br>level 1 (TRUE) output activated by the<br>rising edge of the input and remains in this<br>condition for the set time  |                 | Monostable B<br>This operator generates a level 1 (TRUE)<br>output activated by the rising/falling edge<br>of the input and remains in this condition<br>for the set time   |
|---|---|-----------------|---|
| PASSING MAKE<br>CONTACT   | <b>Passing Make Contact</b><br>In the Passing Make Contact operator the<br>output follows the signal on the input.<br>However, if this is 1 (TRUE) for longer than<br>the set time, the output changes to 0 (FAL-<br>SE). When there is an input falling edge,<br>the timer is cleared.   | En M CTS        | Clocking<br>This operator has up to 7 inputs to control<br>the output Duty Cycle. Related to the<br>selected input, this operator will generate<br>a clock with different duty cycle. It can be<br>used, for example, to pass or receive the<br>status information to or from a PLC<br>More info: "Clocking operator" on page<br>30.  |
|   | <b>Delay</b><br>Delay operator applies a delay to a signal<br>by setting the output to 1 (TRUE) after the<br>set time, against a change in the level of<br>the input signal.  | LONG DELAY      | Long delay<br>This operator allows to apply a delay (up to<br>15 hours) to a signal by setting the output<br>to 1 (TRUE) after the set time, against a<br>change in the level of the input signal<br>Available with M1S.  |
|   | Delay line<br>When the signal IN is moved to 0 logic<br>level, this operator inserts a delay to a<br>signal carrying the output OUT to 0 after<br>the time set. If before the end of the set<br>time the input IN returns to 1, the output<br>OUT still generates a pulse signal with this<br>duration: about 2 times the response time<br>plus the delayed time set. | LONG DELAY LINE | Long delay line<br>When the signal IN is moved to 0 logic<br>level, this operator inserts a delay (up to<br>15 hours) to a signal carrying the output<br>OUT to 0 after the time set. If before the<br>end of the set time the input IN returns to<br>1, the output OUT still generates a pulse<br>signal with this duration: about 2 times the<br>response time plus the delayed time set. |
|   | Differences with dealy: delay Line operator<br>does not filter any input interruptions less<br>than the set time.   |                 | Differences with dealy: long delay Line<br>operator does not filter any input interrup-<br>tions less than the set time.<br>Available with M1S.   |
| Delay Comparator<br>This operator allows to compare the value of the Long delay timer with the set threshold volue.<br>This operator allows to compare the value of the Long delay timer with the set threshold volue.<br>(FALSE) until the timer value is lower than the threshold value. The output will be set to the origination of the threshold value.<br>Warning: the Delay Comparator operator can only be connected to an output of a Long delay timer with M1S. |   |                 | vill be set to 1 (TRUE) for timer values equal  |

#### Pre-reset operator

#### Pre-reset



This operator allows to memorize the status of the input signal following the correct sequence of the two PreReset and Reset signals: transaction (0-1-0) of the PreReset signal followed (within the set time) by the transition (0-1-0) of the Reset signal.

The 0-1-0 transition of the signals, to be considered valid, must take place in a time between 500 msec and 5 sec.

Available with M1S.

#### Reset operator



#### Reset

This operator resets the Mosaic system in presence of errors on the inputs or outputs.

This operator generates a reset of the system when the corresponding input is a double transition OFF-ON-OFF of less than 5s.

More info: "Reset operator" on page 29.



#### Safety Guard Lock operator



#### Guard Lock

The Guard lock operator controls locking/ unlocking of an electromechanical guard lock by analysing consistency between the Lock command and the status of an E-GATE and a FEEDBACK. More info: "Guard Lock operator" on page 32.

#### Network operator



#### Network

Is a serial connection (Loop) of several Mosaic Master unit (with possible expansions). This operator allows stop and reset commands to be distributed in a simply Mosaic network.

More info: "Network operator" on page 32.



The Digital Comparator operator allows to compare a series of input signals (from 2 to 8 max.) with a decimal constant (range 0 to 255).

The input In1 is the LSB (least significant bit) while the input In8 (or lower if the number of inputs selected is less than 8) is the MSB (most significant bit).

The comparators are: <Less; > = Greater or equal; > Greater; <= Less or equal; = Equal; ! = Different

Selecting "Signal Comparison", the Digital comparator operator will compare the first four inputs A (In1\_A ... .In4\_A) and the second four inputs B (In1\_B ... .In4\_B).

The comparators are the same as described above.

Available with M1S.

Digital comparator

#### Counter operators



#### Counter

Counter operator is a pulse counter that sets output Q to 1 (TRUE) as soon as the desired count is reached. There are 3 operating modes: Automatic, Manual, Automatic + Manual.



#### Counter Comparator

This operator allows to compare the counter value with the set threshold value. The output will be kept at 0 (FALSE) until the counter value is lower than the threshold value. The output will be set to 1 (TRUE) for counter values equal to or greater than the threshold value.

Warning: the Counter Comparator operator can only be connected to an output of the Counter operator.

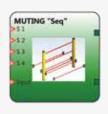
Available with M1S.

#### Muting operator objects



#### L Muting

With 2 Muting sensors for one-way openings (exit only). Suitable solution for any applications of pallet exit.



#### T Muting "Sequential"

With 4 Muting sensors for two-way openings (entry/exit). Suitable solution for transparent material and application with presence of a pallet with reduced width or not centred with respect to the conveyor.

More info: T Muting «Sequential» on page 30.



#### Muting Override

Are available two selectable functional mode: Override with hold to run action Override with one pulse action.

More info: "Muting Override" on page 30.



#### T Muting

With 2 Muting sensors for two-way openings (entry/exit). Suitable solution for the most common pallet infeed/outfeed applications.



#### T Muting "Concurrent"

With 4 Muting sensors for two-way openings (entry/exit). Suitable solution for transparent material and application with presence of a pallet with reduced width or not centred with respect to the conveyor.

More info: T Muting «Concurrent» on page 30.





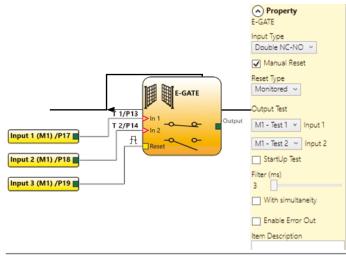
### INSIGHTS

### A DETAILED LOOK INTO THE MOST INTERESTING FEATURES OF MOSAIC MSD

#### Property window

The property window of each function block allows configuring each block parameters in a simple and easy way.

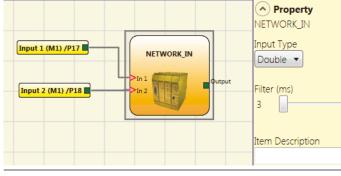
This allows achieving an important level of customisation for each project tailoring Mosaic behaviour to each particular application.



E-gate configuration example

### Network\_In

This function block creates a network input interface connection, generating on the OUT output a high logical level (1) when the line is high, 0 otherwise.



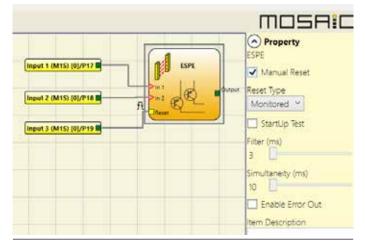
This input can only be allocated to Mosaic Master.

#### Network \_IN Object

This input must be used when Mosaic OSSD or status outputs are connected to the inputs of a second downstream Mosaic or together with the NETWORK operator.

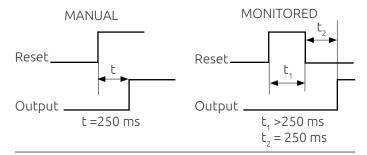
#### Automatic or Manual Reset

Manual Reset: If selected this enables the request to reset each time the area protected by the safety light curtain is occupied. Otherwise, enabling of the output directly follows the input conditions



ESPE configuration example

There are two types of reset: Manual and Monitored. When Manual is selected the system only verifies the signal's transition from 0 to 1. If Monitored is selected the double transition from 0 to 1 and then back to 0 is verified.

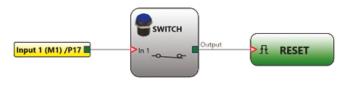


Manual and monitored reset

#### **Reset operator**

This operator resets the Mosaic system in presence of errors on the inputs or outputs.

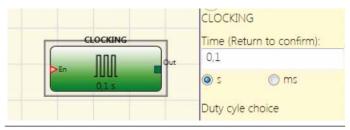
This operator generates a reset of the system when the corresponding input is a double transition OFF-ON-OFF of less than 5s



Connection of Reset operator

### Clocking operator

This operator has up to 7 inputs to control the output Duty Cycle. Related to the selected input, this operator will generate a clock with different duty cycle.



Clocking operator proprerty



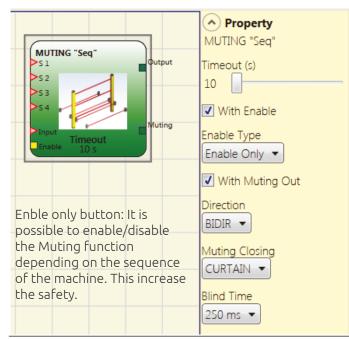
It can be used, for example, to pass or receive the status information to or from a PLC.

Clocking operator connection sample

### T Muting «Sequential»

The activation of the Muting function occurs following sequential interruption of the sensors S1 and S2, subsequently S3 and S4 sensors (without time limit). If the pallet proceeds in the opposite direction the correct sequence is: S4, S3, S2, S1.

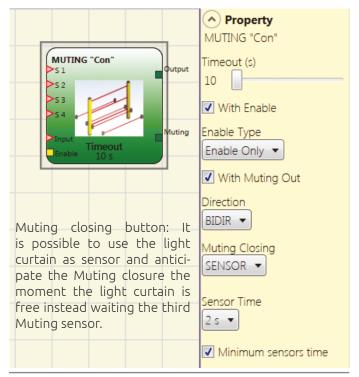
Preliminary condition: The Muting cycle can only start if all the sensors are 0 and the inputs are 1 (sensor and light curtain free).



Example of Sequential Muting parameters configuration

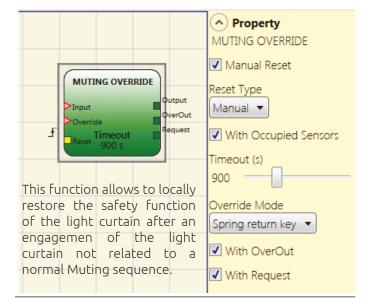
### T Muting «Concurrent»

The activation of the Muting function occurs following interruption of the sensors S1 and S2 beams and then of the sensor S3 and S4: the two sensor must be interrupted within a configurable safety timeout (sensor time) the maximum duration of the Muting status is limited by a timeout. S1 --X sec. --> S2 ---t---S3 --X sec. --> S4 Where t is a value that depends on the "timeout", X is the "sensor time". The "Minimum sensors time option" allows to stop the Muting function if the transit in front of the sensors 1-2 and 3-4 takes place with a time less than 150 ms. This allows to detect the transit of much faster than a pallet person.



Example of Sequential Muting parameters configuration

### Muting Override



Example of Muting override configuration



#### Analogic Inputs configuration

The input type "Single" allows to connect one analogue sensor (current or voltage) to the module input. By selecting "Redundant", it will be possible to connect two analogic sensors to the input of the module. The signals of the two sensors are analysed and compared between each other.

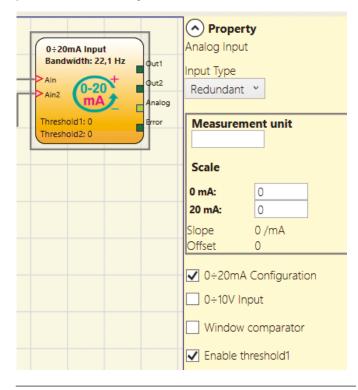
The "Measurement unit" field allows to enter the engineering units measured through the sensor (i.e. Kg,  $^\circ$  C, etc.).

In the "scale" fields, it's possible to insert the minimum value of the quantity corresponding to the minimum signal coming from the sensor in the "4mA or 0V" box and the maximum value in the "20 mA or 10V" box.

The two check boxes "0-20 mA" and "0-10 V" allows to define the sensor output type: voltage instead of current.

The windows comparator selection activates an analogue window comparator. The output OUT1 will be 1 (TRUE) when the value read by the sensor is between the two thresholds. It will be 0 (FALSE) when the value read by the sensor will be outside the two thresholds. It is also possible to enter a hysteresis value.

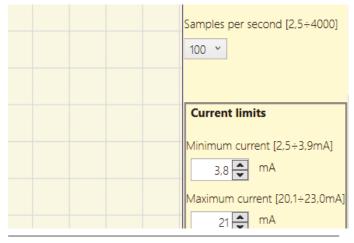
Threshold 1,2 fields represents the threshold above which the output OUT1 will be 1 (TRUE). Below the set threshold the output OUT1 will be 0 (FALSE). Also in this case it is possible to insert a hysteresis value.



Analogue inputs configuration parameters

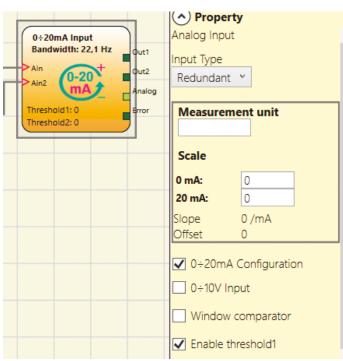
In the fields "Samples per second (2.5-4000)" it's possible to enter the value that determines the number of samples per second of the analogue input signal.

Moreover, It is possible to enter the limit values below which (Minimum current value) or above which (Maximum current value) the ERROR output will be activated.



Sample per second of the analogue input configuration

Are also available a series of values that allows to check the correct operation of the analogic sensors.

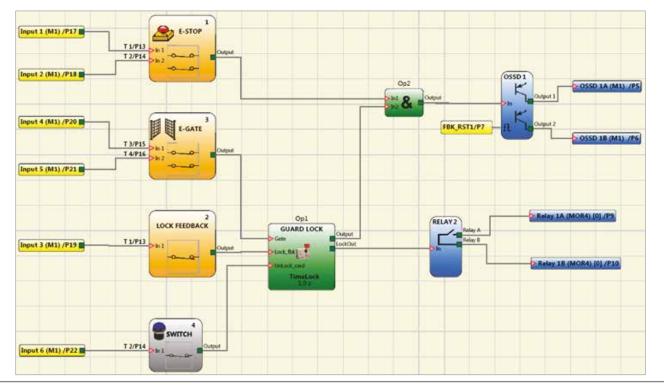


Sensor anomaly configuration



### Guard Lock operator

The Gate input is connected to the functional block e-gate. This is an example of Guard Lock configuration.

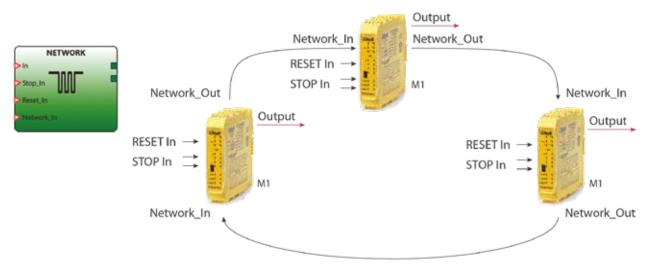


Sample of Guard Lock operator connection

- 1. The Lock\_fbk input is connected to the functional block Lock\_fbk (feedback from the lock)
- 2. The UnLock\_cmd input (unlocks command) is connected to an input switch
- 3. The signal output will be 1 if the door is closed and the guard lock is locked
- 4. When an unlock command is applied to the input (UnLock\_cmd), the output signal will be set to "0" and after a programmable time Time\_Lock (2 sec. in the example) the guard lock is unlocked through the LockOut output

### Network operator

It allows loop connection (Loop) of several Mosaic Master units (with expansions). This operator allows stop and reset commands to be distributed in the Mosaic network.



#### Network connection



#### Speed monitoring object configuration example

Example of speed monitoring of one axis. Monitoring of stand still and speed control with selectable 2 thresholds

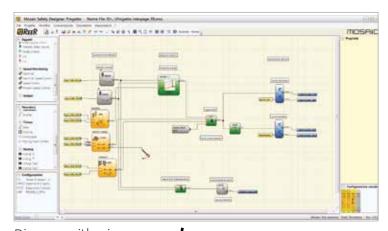


|                  | Proprietà STAND STELL AND SPEED CONTROL              |                       | Velocità zero (-<br>[giri/min]          | -60)     |
|------------------|--|-----------------------|---|----------|
| Axis 1 (MV2) (R) | Rotativo   | Freque<br>(>= 0       | erza velocită ze<br>(7Hz)               | o        |
|                  | Dispositivo di misura                                | [Hz]                  | Moura                                   | Verifica |
|                  | Encoder + proximity *                                | fu=                   | 166,667                                 | 8,333    |
|                  | Abilita Uscita Direcione                             | f m =                 | 158,334                                 | 7,916    |
|                  | Decisione Directione<br>Bidirectionale +             | 4000                  | u 1 (< 60000)<br>[giri/min]             |          |
|                  | Numero sogle<br>Due Sogle                            | and the second second | a 2 (< 60000)<br>[giri/min]             |          |
|                  | Scelta Proximity                                     | Freque                | maa 1                                   |          |
|                  | PHP 3 Fil NC .                                       | [H2]                  | Midura                                  | Verifica |
|                  | Moura  | fig =                 | 66666,667                               | 3333.33  |
|                  | Rispluzione Encoder (< 40000)<br>1000 [impulsi/giro] | f==                   | 63333,334                               | 3166,66  |
|                  | Verifica   | Freque                | rrca 2                                  |          |
|                  | Risoluzione Proximity (< 200)                        | (Hz)                  | Moura                                   | Ventca   |
|                  | 50 (impulsi/giro)                                    | f <sub>M</sub> =      | 100000                                  | 5000     |
|                  | Gear Ratio   | fer                   | 95000                                   | 4750     |
|                  | 1 (1 to 100 step 0.1)<br>Esterest (%)                | 1.00                  | i<br>litazione Error (<br>cione Oggetto | Dut      |

Speed monitoring object configuration example

#### Interpage operators

Interpage operators is a label assigning a name to a certain logical interconnection.



Considerable simplification and readability of the diagram.

Diagram with wires

To simplify the names

downmenu,thatletsyou

choose the name of the

"Interpage out" among

those assigned to the

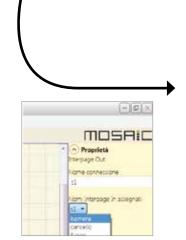
a drop-

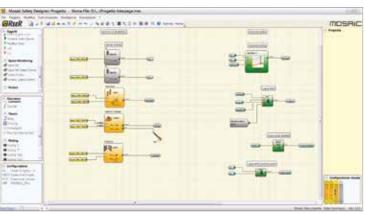
"Interpage

assignment

operators

In"





The same diagram with Interpage function applied

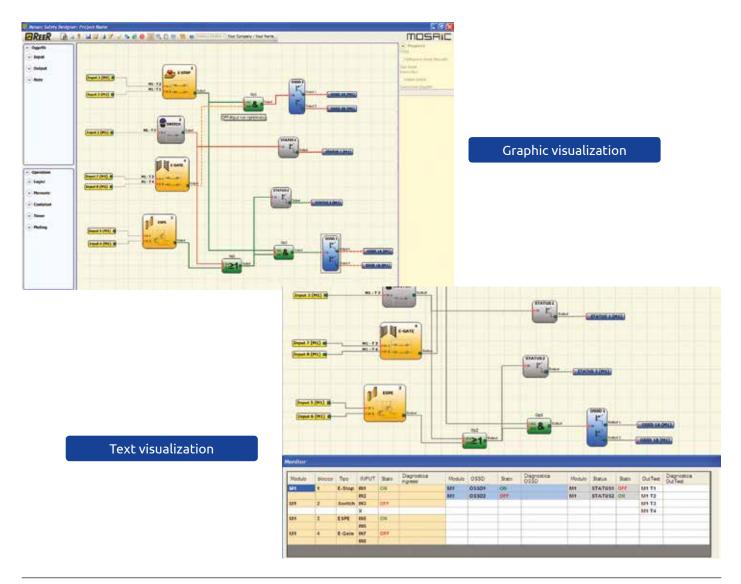
Interpage operator advantages

## MOSAIC )

### **REAL TIME MONITOR**

The I/O MONITOR allows the real-time monitoring of all the I/Os of a Mosaic system and the diagnostic information about a working system.

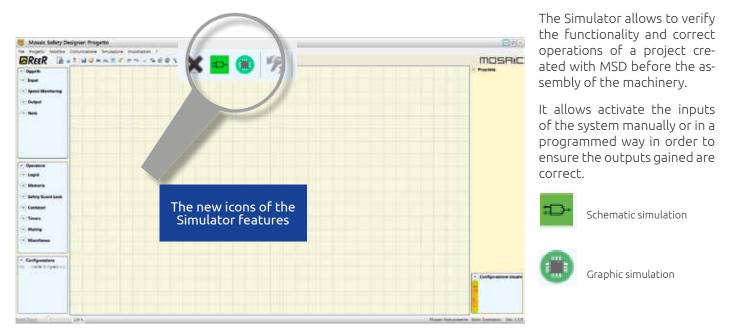
## VISUALIZATION



Real-time Monitor



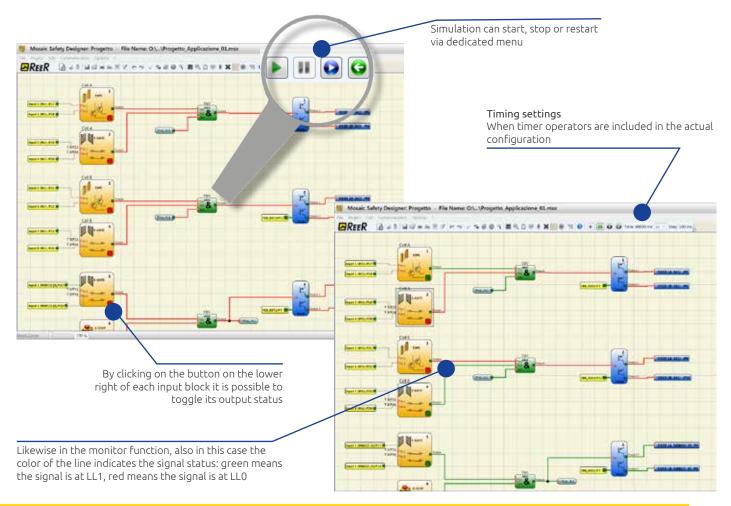
### SIMULATION FUNCTION



NOTE: the simulation feature is available with MSD version 1.5 and M1 firmware version 3.0 or higher.

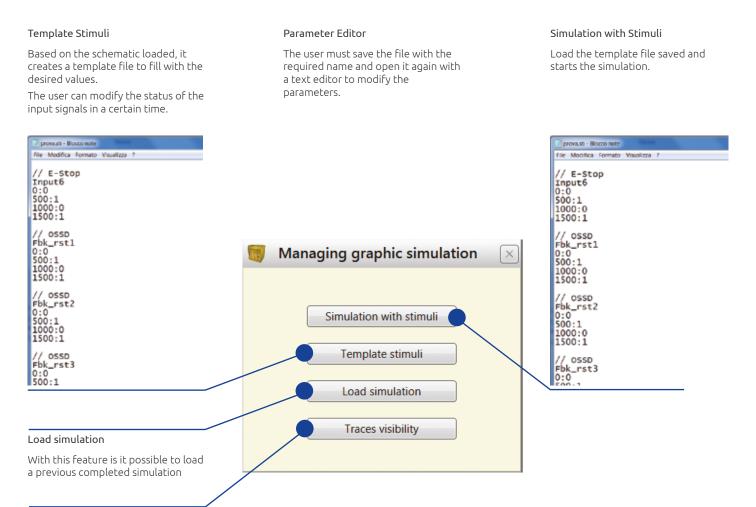
### SCHEMATIC SIMULATION

The schematic simulation allows to "start" the project via a dedicated menu and to operate directly on any of the inputs to verify the logic of the system.



## MANAGING GRAPHIC SIMULATION

The graphic simulation allows to load a number of programmed inputs status change and to verify the logic of the system as a graphical output diagram. This methodology allows to create templates replicating the exact functionality of a machinery and apply them on different projects.

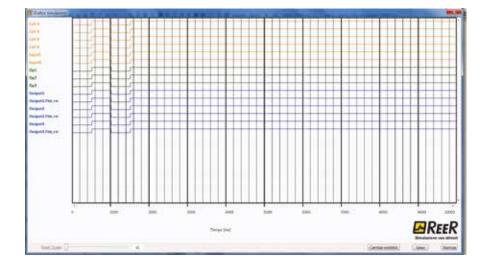


#### Traces visibility

With this option the user could select the traces (waveform signal) to be displayed in the graph or not



At the end of the simulation a graph with all the resulting signals is showed.



HSD SOFTWARE

### MESSAGES EDITOR FOR THE HM1 DISPLAY

HSD is the editor software that allows programming of the HM1 device.

HM1 can be connected to the Mosaic system in 3 ways:

- Wired to a status output connected to the serial operator, asynchronous serial connection. Max 32 status displayed. See picture 1
- Wired to 2 status outputs connected to the serial operator, synchronous serial connection. Max 16 status displayed. See picture 2
- 3. Wired to the serial MBx module via RS 485 serial port, All I/O statuses and diagnostic displayed

| Dutput   | Output STATUS 1 (M1) /M8                     |
|--|--|
| SERIAL OUTPUT<br>Din2<br>Din2<br>Din3<br>Din3<br>Din4<br>Clock | STATUS<br>In Output STATUS 2 (M1) /M12       |
|  | STATUS<br>In Cutput STATUS 2 (MI8O2) [0]/M12 |

MOSAL

HM1 connections type

The digital signals from the output status or serial operator can be converted to display messages on the display HM1 through this HSD editor software.

| SHSD                        | e Valainza « Properto , Recore et Lacore El Depose O r   | 30) <b>#</b> , 1                           |
|-----------------------------|--|--|
| DOMESTIC: NO DOM            |  |  |
|                             | (2) 0 H 0 0 H 0 2 C (0 H balance + 0.2000) ≥ 100 5 + 2.0   |  |
| Gestione Progetto +         | Display HML - test   | E Pagine TE Ladder & Brouchi Fundione      |
| - Fail I a Bag              |  | Appungi Yarubite: a Crimita radutini       |
| Maint Ares Progr            |  |  |
| W DOWN OF FRIDE DATE OF     |  |  |
| Two:2 + Ases Bukan          |  |  |
| \$ 75 ) Save EEPRO          | HM1  |  |
|                             |  |  |
|                             |  |  |
|                             |  |  |
| vini -                      |  |  |
| Finestra Proprieta          |  |  |
| Nessana Variabile Selecton  |  |  |
| Numerican estates           | B feguni I - Strain I (-Bigs ) I )   |  |
|                             | gi Castla Stummet i Teosa  | V Debugger O Caratteri Speciali Militare + |
|                             | Cerce at Tam   |  |
|                             | Trea Solitaid  |  |
|                             | A Treve (ACT+FE) O Treve la prima seconaria (ACT+SEC) O Briomacioni                                      |  |
| 100 million and 100 million | Precidente (ACT-PE) Prese forcements Presidente Solu Parcie Snare  |  |
|                             | Successes (421+17) O True Communica Successes Menuscole / Menuscole Ungue : Italiano II                  |  |
|                             |  |  |
| (X)                         |  |  |
|                             |  |  |
|                             |  |  |
|                             |  |  |
|                             |  |  |
|                             |  |  |
|                             |  |  |
|                             |  |  |
|                             |  |  |
| Witaliand   Porta COM: COM: | 1    🖞 Baud Rule Onime: 115200   🕊 Tantera: Standard    - Itorie: Piccole   I Terria del Piogramma : Bio |  |

HSD main screen

## APPLICATION EXAMPLES

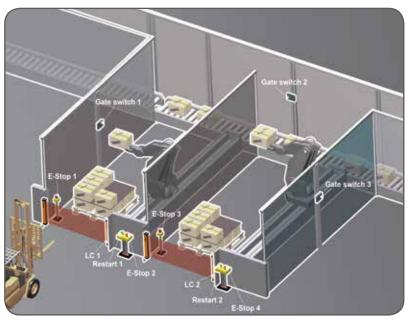
## SAFETY MANAGEMENT OF A PALLETIZING SYSTEM WITH TWO ROBOTIC CELLS

The system comprises a conveyor that transports boxes to two robotic palletization cells.

The machine is completely protected by a fence with three access gates (one for each robotic cell and one for the conveyor area) equipped with a safety switch. When the gate of the robotic cell is open, the corresponding robot stops. When the conveyor area gate is open the entire plant stops.

The completed pallets are collected by a forklift truck through the access gate which is protected by a safety light curtain. The access of the forklift truck for collecting the pallet, when the robot is stopped in the rest position, by reason of the safety light curtains, prevents the robot to start.

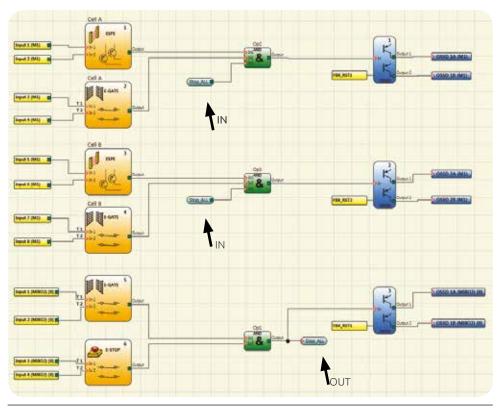
In all other phases of processing, occupation of each light curtain causes the related robot to stop. The related manual restart control is located close to each light curtain. The system is equipped with four emergency push buttons (e-stop).



Total safety devices: 2 safety light curtains, 2

restart buttons for the safety light curtains, 3 safety gate switches, 4 emergency push buttons.

Using conventional components – safety relay modules – to build up the safety circuit, it would be necessary to use at least six safety modules, wired to each other in order to perform the required functions: 2 safety relays for the light curtains, 3 safety relays for the gate switches, 1 safety relay for the emergency stop chain.



16 inputs - 4 OSSD pairs - 8 test outputs - 4 signal outputs

#### Solution with Mosaic

Using Mosaic to build up the safety circuit, it is sufficient to use:

- 1 M1 or M1S Master unit
- 1 MI8O2 expansion unit

Note 1: the Reset buttons not displaаге on the diagram ved because they are directly connected to the feedback of the OSSD safety outputs (inputs FBK RST1, FBK RST2. The 4 E-STOP are connected in series and in the diagram they are represented with a single block.

Note 2: 3 operators Interpage (2 In and 1 Out) were included in the diagram. These allow you to link the inputs and outputs of the logic gates "&" without having to draw the line.



### SAFETY MANAGEMENT OF A MACHINING CENTRE WITH ALTERNATE LOAD / UNLOAD

The operator is required to load and unload the workpiece. The machine is protected by two horizontal safety light curtains. In this case, each light curtain must be equipped with the Muting function so as to permit access to the hazardous area by personnel during the non-hazardous part of the machine cycle.

Depending on the position of the tool, which is the hazardous element, one of the two light curtains (the one facing the tool working area) is active, while the other is muted so that the operator can load/unload the workpiece.

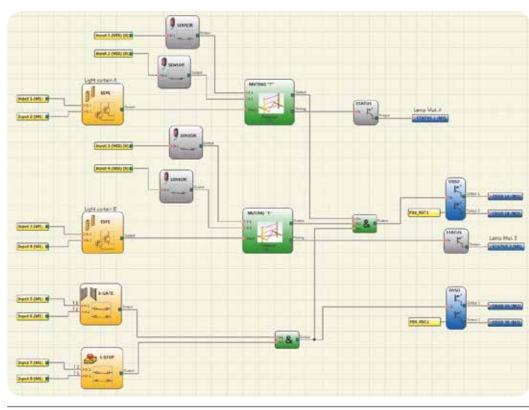
The Muting condition of the two safety light curtains will then be inverted when the tool is required to operate on the opposite side of the machine.

by two see, each sous part Hunt multiple switch 1 Hunt switch 1

The machine is completely protected by a fence with an access gate equipped with a safety switch. When the gate is opened, the machine stops. The related manual restart control is located close to each safety light curtain. The system is equipped with three emergency push buttons which, if activated, stop the machine.

Total safety components: 2 safety light curtains, 2 restart buttons for the safety light curtains, 1 safety gate switch, 3 emergency push buttons.

Using conventional components – safety relay modules – to build up the safety circuit, four safety modules would be necessary: 2 safety modules for the safety light curtains with Muting function, 1 safety module for the gate switch, 1 safety module for the emergency stop.



16 inputs - 2 OSSD pairs - 8 test outputs - 2 signal outputs

### Solution with Mosaic

Using Mosaic to build up the safety circuit, it is sufficient to use:

- 1 M1 or M1S Master unit
- 1 MI8 expansion unit

NOTE: the Reset buttons are not displayed on the diagram because they are directly connected to the feedback of the OSSD safety outputs (inputs FBK\_ RST1, FBK\_RST2.

The 3 E-STOP are connected in series and are represented in the diagram with a single block.

The diagram also shows 2 status outputs used to drive the indication lights of the active Muting.

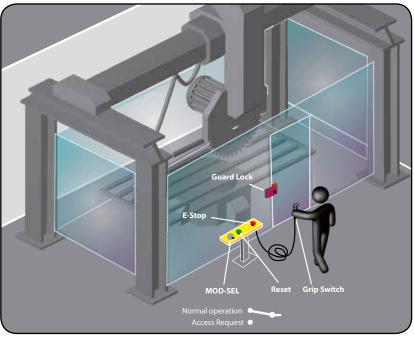
## SPEED MONITORING FOR A HAZARDOUS TOOL

In this example, to place or remove tooling or to perform maintenance activity where is necessary for the operator to enter the dangerous area.

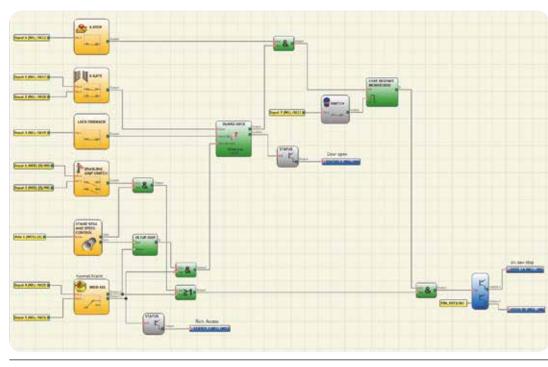
As long as the tool is working at the normal speed the GUARD LOCK is locked and the access to the hazardous area is not allowed.

Access to the hazardous area is allowed either when the working cycle is over or when the operator switches the MOD SEL to "Access Request". When the tool stops the lock is unlocked and allows the opening of the door. In this case the speed controller verifies that the tool is stopped (zero speed).

For maintenance, it is necessary that the system operates at reduced speed. The operator will have to act on the selector (MOD-SEL) and bring it in the "Maintenance" position. When the tool stops the lock is unlocked and allows the door opening. If the tool has to be kept moving for



maintenance reasons as the operator is inside the hazardous area, this is possible through the Grip Switch. The speed monitoring device detects whether the speed of the tool is under a defined threshold set through the MSD. If the threshold is exceeded or the Grip Switch is released the machine is immediately stopped.



On the perator panel are available the emergency stop (e-stop) button and reset button to restore the normal operating conditions of the safety lock after the operator intervention.

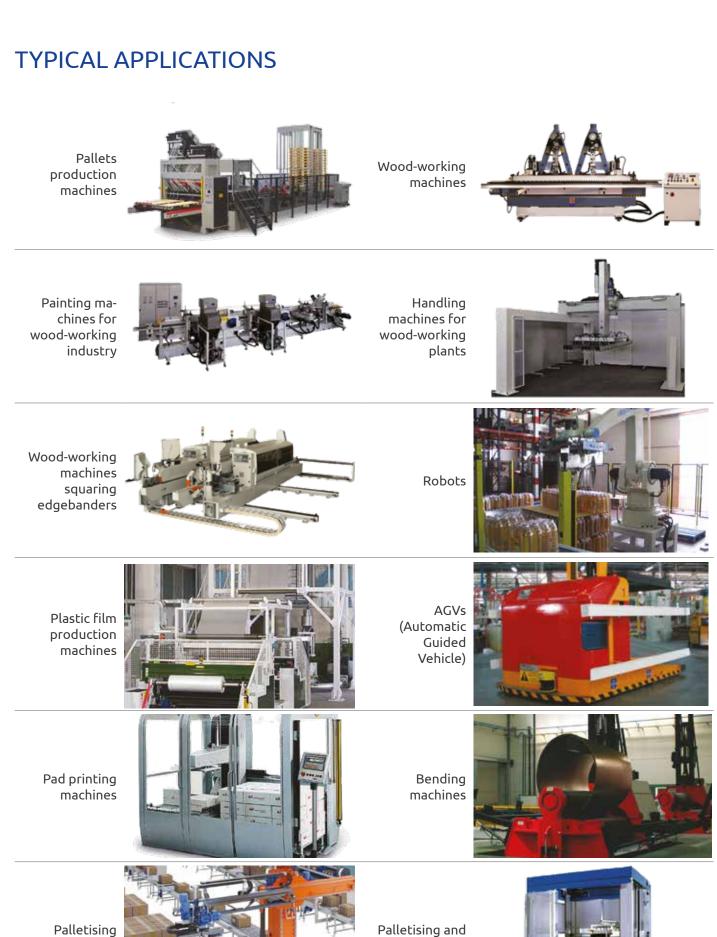
Using Mosaic to build up the safety circuit, it is sufficient to use:

- 1 M1 or M1S Master unit
- 1 MI6 expansion unit
- 1 MV0 expansion unit for safety speed monitoring

#### Safety speed monitoring

### Comments

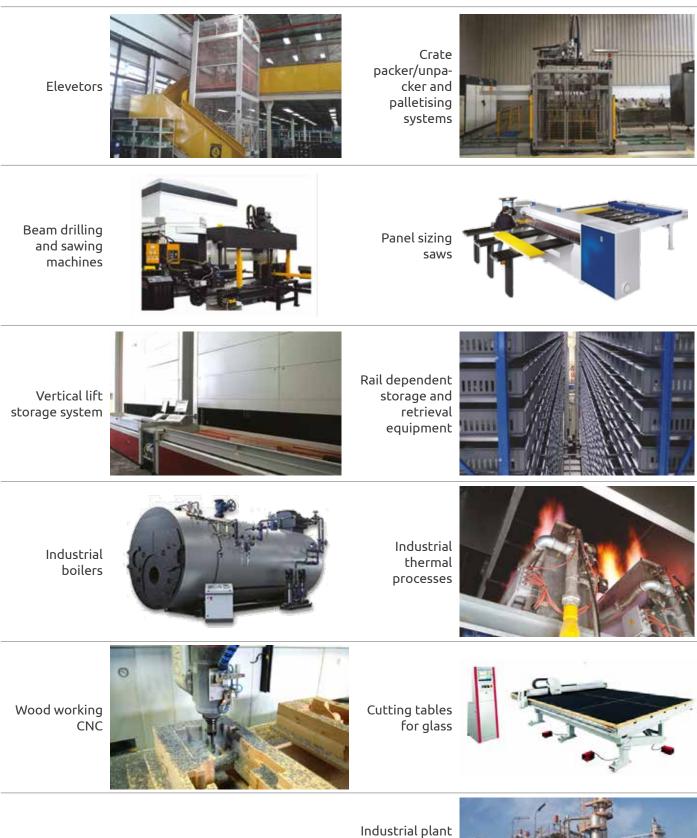
Using Mosaic, all the safety logic circuitry is implemented using the graphic interface and not by hard-wiring the outputs of the relay modules to each other. Correct functioning of the logic circuitry is checked during the design phase by the **validation function** and can be tested with the **simulation** and **monitor function** during installation. During the design phase, safety functions can be easily added or removed, for example adding other sensors or zones. Start up tests can be inserted in order to detect any attempt of by-passing the safety system, which is always a possibility with traditional relay modules.



bottling plants

Palletising systems MOSAIC





application with MA4 Analogic imput unit:

Loading cells (weight, compression and traction measurements), pressure switches, temperature measurements, flow measurements, level measurements, etc.



## CUSTOMER SERVICE



# REER Customer Service

## We put our Customers always first

ReeR after sales service is committed to support all customers that need technical guidance regarding functionality, handling and installation of our products.

Customer Service Hotline +39 011 24 82 215 Monday to Friday 8.30 - 12.30 and 13.30-18.00 (CET)

> or contact aftersales@reer.it

For product returns please visit www.reersafety.com for further information.



#### 60 years of quality and innovation

Founded in Turin (Italy) in 1959, ReeR distinguished itself for its strong commitment to innovation and technology.

A steady growth throughout the years allowed ReeR to become a point of reference in the safety automation industry at a worldwide level.

The Safety Division is in fact today a world leader in the development and manufacturing of safety optoelectronic sensors and controllers.

ReeR is ISO 9001, ISO 14001 and ISO 45001 certified.





ReeR SpA Via Carcano, 32 10153 Torino, Italy

T +39 011 248 2215 F +39 011 859 867

www.reersafety.com | info@reer.it







Issue 2 - Rev. 1.3 October 2019 8946225 MOSAIC - English

Printed in Italy

